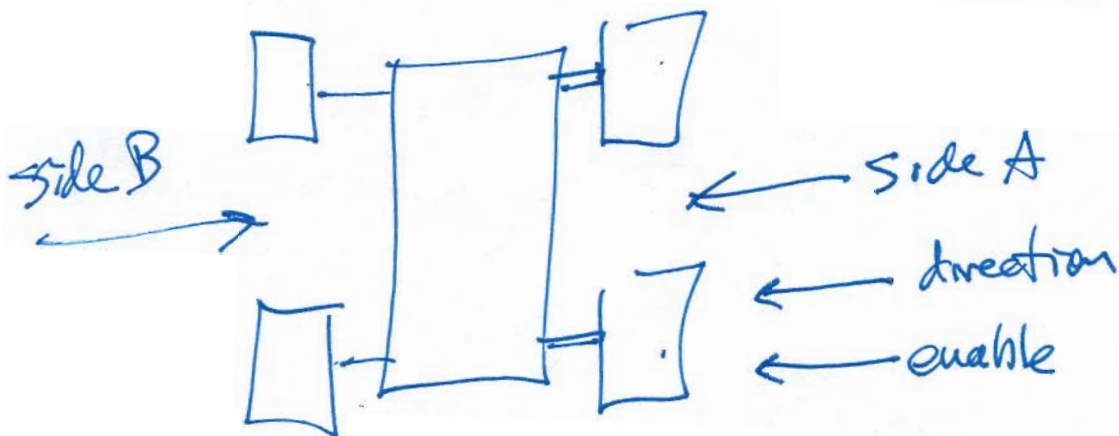
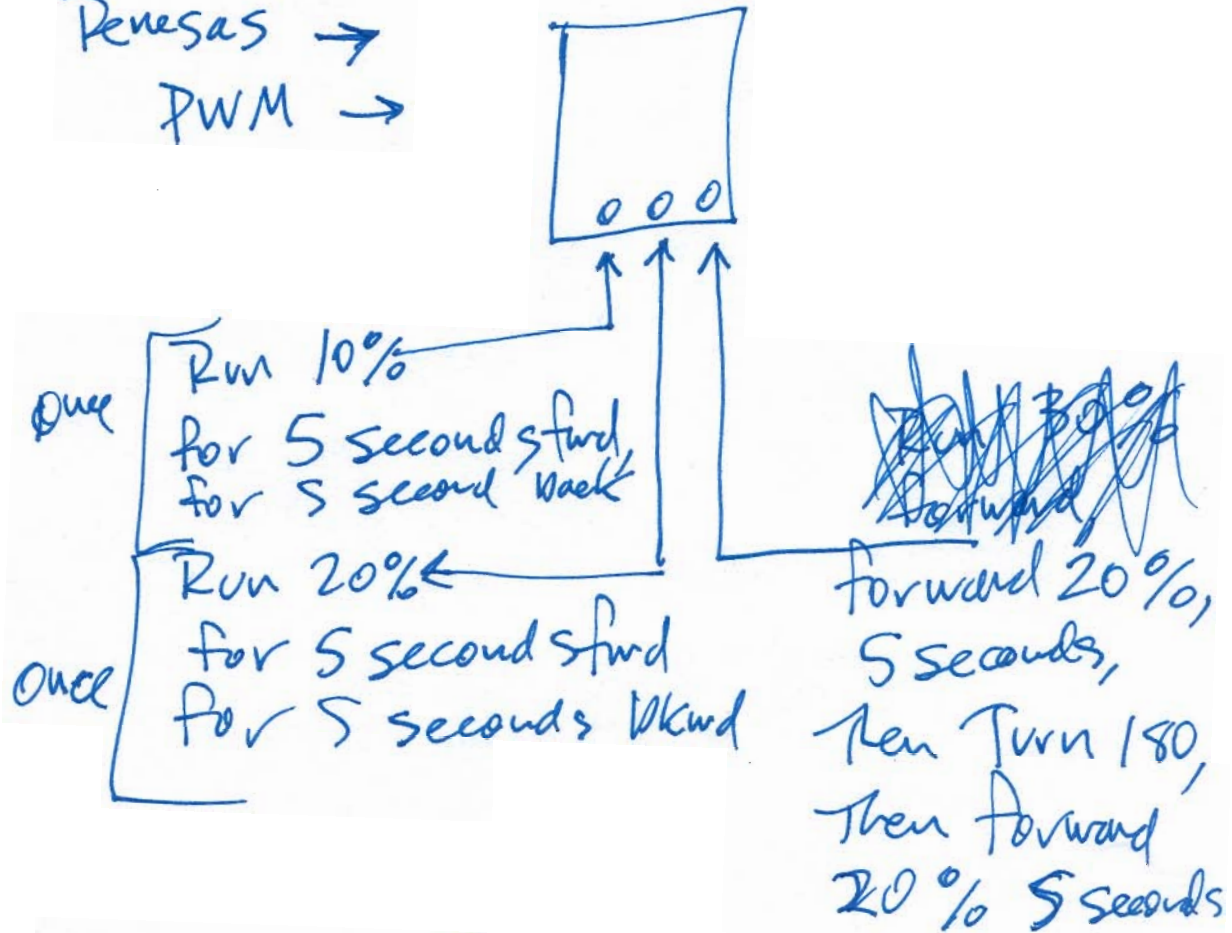


ECGR 4161 - Extra Notes - 3/25/09

Lab → Vehicles, add driver board,

Penasas →
PWM →



$f = 1\text{kHz}$



ECGR4161 - Extra Notes - 3/25/09

Steps → Software

(2)

- 1) Design (Algorithm) - Renesas
- 2) Program
- 3) Code Review
- 4) Download, test the outputs with
a scope (Renesas)
- 5) Hookup to robot on bench - test
- 6) ~~Mount~~ Mount the boards to the robot
- 7) Test outside