

## **M16C/62**

### **Using the Expanded Memory Mode with the M16C/62**

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#### **1.0 Abstract**

The following article introduces and shows an example of how to access external memory using the expanded memory mode of the M16C/62 series of microcontrollers.

#### **2.0 Introduction**

The Renesas M16C/62 series of microcontrollers is a 16-bit family of MCUs, based on Renesas' M16C CPU core. These parts provide high memory efficiency, power-saving ability, low noise emission, and improved noise immunity. The M16C/62 part series can be used in many applications such as office equipment, PC peripherals, portable devices, automotive, cameras, audio, and so on.

This application note shows how to configure and use the expanded memory mode on the M16C/62 series of microcontrollers.

#### **3.0 Memory Expansion Mode**

There are three processor modes used with the M16C/62 series of microcontrollers. For each processor mode, the memory map functions of some pins and external access space differ. The three processor modes are as follows:

- Single-chip mode—Only internal memory space can be accessed.
- Memory Expansion mode—External memory can be accessed in addition to all the internal memory.
- Microprocessor mode—External memory along with internal SFR and RAM areas can be accessed. Internal ROM cannot be used.

For this application note, memory expansion mode is demonstrated. This allows use of all the internal memory areas (SFR, RAM, ROM) and some external memory. In this mode, some of the pins need to function as the address bus, data bus, and control signals for accessing the external memory. The number of pins affected depends on the bus and register settings. Once expanded memory mode and the control settings are selected, the affected pins become dedicated to external memory and can no longer be used for other I/O functions.

The desired processor mode is set by the processor mode bits in the processor mode register (PM0) and the CNVss pin. To select memory expansion mode, the CNVss pin is tied to Vss and the processor mode bits are set to "012". When programming in C, the processor mode is set in the startup file (nct0.a30). Figure 1 is an example for setting the processor mode bits.

```

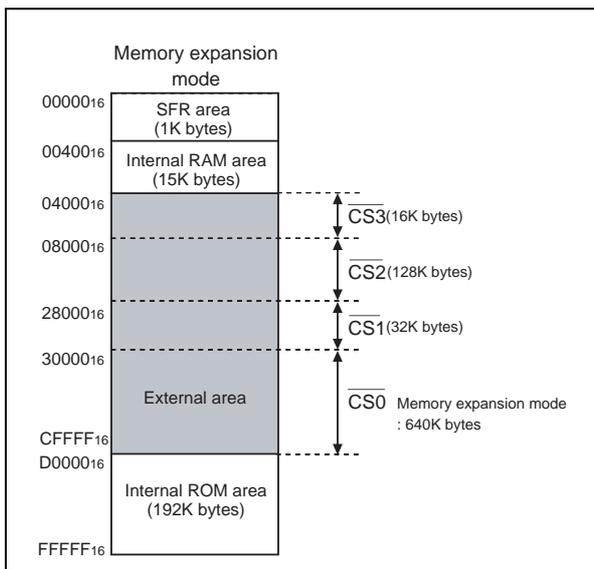
start:
;-----
; after reset, this program will start
;-----
    ldc #istack_top,    isp ;set istack pointer
    mov.b #02h,0ah      ; disable protect reg
    mov.b #05h,04h      ; set processor mode pm0
    mov.b #00h,05h      ; set pm1
    mov.b #00h,0ah      ; enable protect reg
    mov.b #07h,08h      ; enable CS2 & CS1 output with wait state
    ldc #0080h, flg
    ldc #stack_top, sp  ;set stack pointer
    ldc #data_SE_top, sb ;set sb register
    ldintb #VECTOR_ADR
  
```

**Figure 1 Setting the Processor Mode Bits in ncr0.a30**

The bus settings and control signals can also be customized for different configurations. The external bus width can be set to either 8 bits or 16 bits by connecting the BYTE pin to Vcc or Vss respectively. This does not affect the internal bus, which is always fixed to 16 bits.

The read/write signal configurations are set in the processor mode register (PM0). There are two combinations of R/W signals. For a 16-bit data bus, select between the RD, WR, and BHE signals or the RD, WRL, and WRH signals. When using an 8-bit bus, always use the RD, WR, and BHE signals.

The chip select area used for the external memory must be enabled in the chip select register (CSR). The chip select register determines if pins P44 to P47 output the chip select or if they are used as GPIO. The chip select register also has bits that determine if a wait state should to be added to each individual chip select area. See the specification for each specific microcontroller for exact chip select memory ranges. Figure 2 is an example of a memory map for an M16C/62 microcontroller in expanded memory mode.



**Figure 2 Example Memory Map with Chip Selects for Expanded Memory Mode**

Other control signals used are the RDY and HOLD signals. The RDY signal is used for any external device that requires a long access time. The HOLD signal is used to transfer the bus privileges from the CPU to an external device.

**Note:** If the RDY and/or HOLD signals are not used, they must be connected to Vcc or the MCU could be permanently stuck in a wait state.

More detailed information on expanded memory, processor modes, and bus settings can be found in the M16C/62 specification and user's manual.

### 4.0 Using Expanded Memory with the PC4701 Emulation System

Some special considerations are required when using expanded memory with the PC4701 emulator. To access any external memory with the emulator, the external memory area must first be mapped using the emulator/debugger software PD30. When PD30 is first started, all memory except for the SFR area is mapped as internal memory.

First, determine the external memory range that will be used according to the chip select that is being used. This external memory area must be mapped to external. Open a script window in PD30 and use the map command to change the memory range that is being used to "External" (example: "map 8000, 9000, ext"). This maps the memory range 8000h to 9000h as external memory. To check that the changes have been set, type "map" in the command line and a list of the current memory map is displayed.

There is one precaution to observe when using the emulator and the CS2 memory space. The memory addresses, 0FFFC<sub>h</sub> to 0FFFF<sub>h</sub>, are used by the emulator as a stack area. These addresses must remain mapped as internal memory or the program will not reset properly. See the Emulation System manual for more information on this precaution. Figure 3 shows an example of mapping the CS2 memory area around the emulator stack.

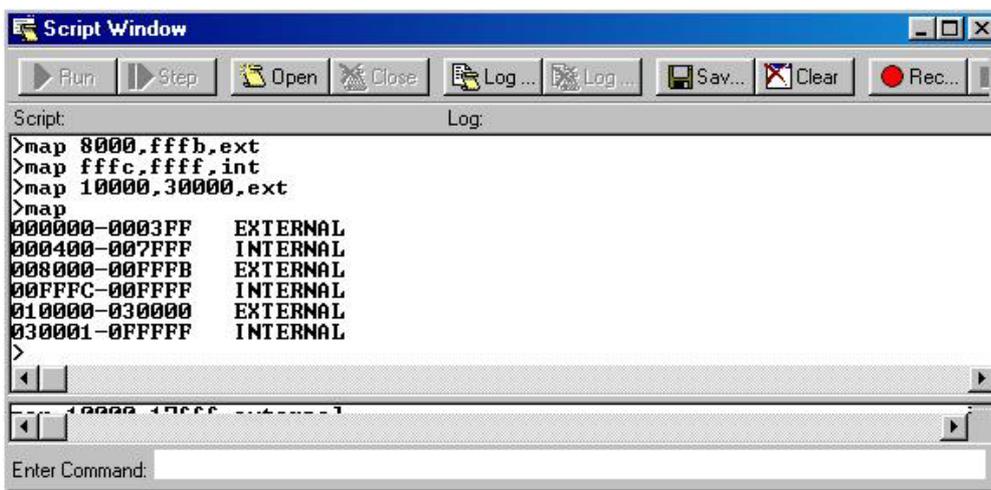
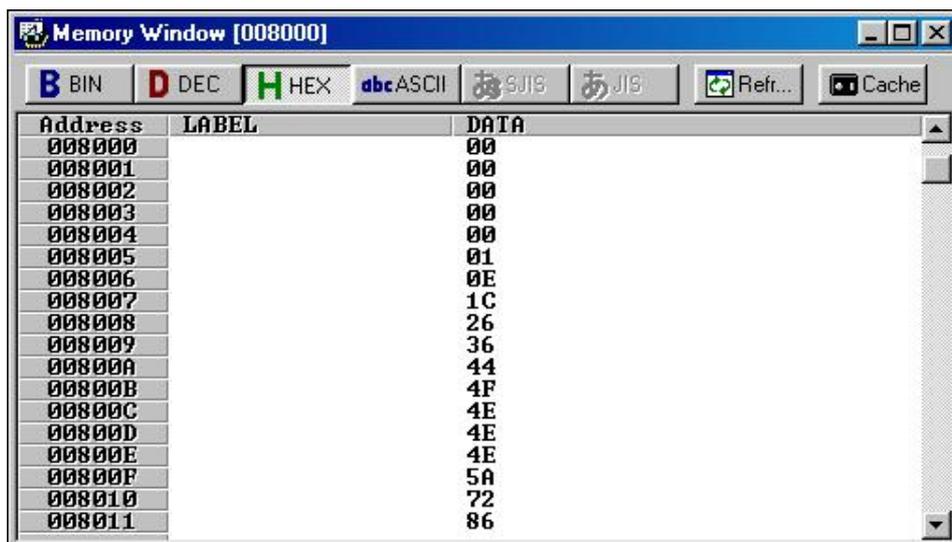


Figure 3 Mapping External Memory in PD30

## 5.0 Implementation

A sample program is included to demonstrate the use of expanded memory mode. This program is written to run on Renesas' MDECE0620 evaluation board. This board allows easy evaluation for any M16C/62 microcontroller. The example program samples the voltage of a potentiometer on the evaluation board and stores this data into the external SRAM on the board. The potentiometer is connected to channel 0 of the A/D converter on the M16C. When the push button S2 is pushed, the A/D value is sampled about every 100 ms and written to the SRAM one byte at a time. An LED (D6) blinks to indicate when the A/D is sampling. When the push button is pressed again, the A/D sampling will stop, all of the A/D data stored in memory is read back, and an average A/D value is calculated. Each time the A/D sampling is started, it returns to the beginning of memory and starts storing data. For simplicity, the sample program is limited to storing a total of 8 kbytes of data.

The memory window in PD30 is used to view the A/D data stored in the external memory. Figure 4 is an example of A/D data stored in the external SRAM on the evaluation board. A/D data storage starts at memory address 8000h. The average A/D value (after sampling is stopped) is also found in the memory window at the average variable address or by using a C watch window.



Address	LABEL	DATA
008000		00
008001		00
008002		00
008003		00
008004		00
008005		01
008006		0E
008007		1C
008008		26
008009		36
00800A		44
00800B		4F
00800C		4E
00800D		4E
00800E		4E
00800F		5A
008010		72
008011		86

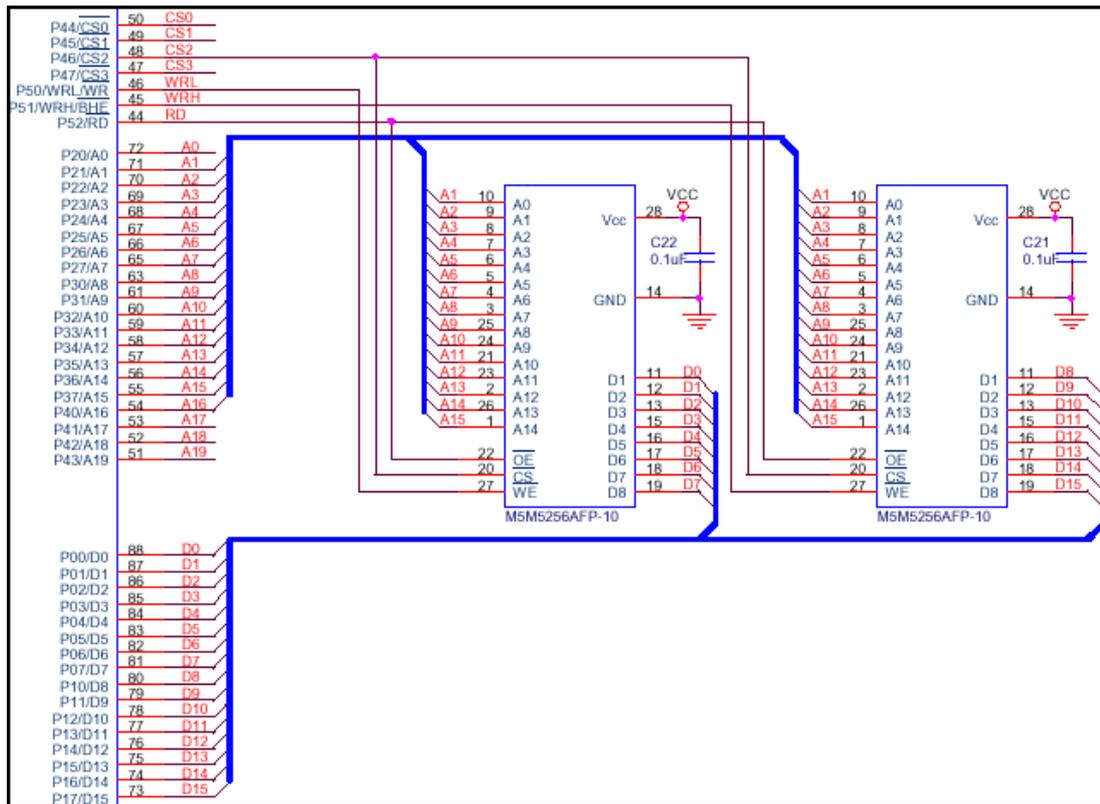
**Figure 4 Mapping External Memory in PD30**

The external memory connections used on the evaluation board and for the sample program are shown in Figure 5. The memory is connected using the 16-bit data bus; the lower byte is connected to one memory chip and the upper byte is connected to the second memory chip. The R/W mode is set to use RD, WRL, and WRH. WRL is connected to the lower byte and WRH to the upper byte. With this configuration, address line A0 is not connected to the external memory because WRL and WRH effectively take its place. It is important to make sure that any unused control signals are tied off properly. [Not shown: The RDY and HOLD pins are connected to Vcc.]

The sample program accesses the memory in both 8-bit and 16-bit modes. Although the memory chips are configured for a 16-bit data bus, the A/D results are 8-bit and writes to the external memory are done 8 bits at a

time. When A/D sampling stops, the results are read from external memory using 16-bit mode. The data are split into two bytes and added together to calculate the average A/D value.

Chip select 2 is used to address the memory. The effective address range using CS2 is 8000h to 27FFFh; this is a total of 128 Kbytes. Each memory chip in our demo contains 32k x 8 bits or 64 Kbytes total memory (8000h – 17FFFh).



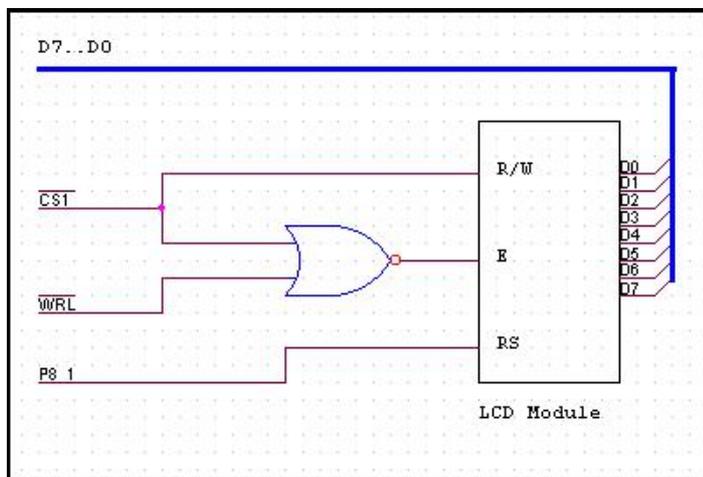
**Figure 5 External Memory Connections**

The potentiometer on the evaluation board is connected to A/D input AN0 on the M16C/62. The A/D is set up for 8-bit conversion, one-shot mode, software triggered, with sample and hold enabled.

The push button (S2) used to start and stop the A/D sampling is connected to an external interrupt on the M16/62. The interrupt used is INT0. Each time the push button is pressed, an INT0 interrupt is generated. A flag monitors the A/D sampling when it is on or off.

The LCD supplied on the evaluation board views the A/D values as they are sampled and the average A/D value when sampling is stopped. Because some of the LCD connections on the board are used for control signals in expanded memory mode, some circuit modifications are needed for the LCD to work with external memory. Figure 6 shows the LCD connections used in the sample program. This configuration allows the LCD to be accessed similar to any external memory. Chip select 1 addresses the LCD, thus writing to any even address (low byte in 16-bit address bus) in the CS1 memory area writes data to the LCD. Writing to an even address causes the WRL signal to go to a logic low level. Writing to an odd address causes WRH to go to a logic low, and

does not enable the LCD. In the sample program the address 28000h is used.



**Figure 6 MDECE0620 LCD Connections When Using External Memory**

The sample program is just one way of using expanded memory mode on the M16C/62 series of microcontrollers.

## 6.0 Reference

**Renesas Technology Corporation Semiconductor Home Page**

<http://www.renesas.com>

### E-mail Support

[support\\_apl@renesas.com](mailto:support_apl@renesas.com)

### Data Sheets

- M16C/62 datasheets, 62aeds.pdf

## 7.0 Software Code

```

/*****
*
*   File Name:  main.c
*
*   Content:    This program demonstrates using expanded memory on the
*               MDECE0620 evaluation bd.  When S2 is pressed, A/D measurements
*               are taken from R11 (pot.) at 100ms intervals and stored in
*               external memory.  When S2 is pressed again, the A/D sampling
*               stops, the data is read from memory and an average A/D value
*               is calculated.
*
*               Date:    9-28-2001
*
*   Copyright 2003 Renesas Technology Corporation
*   All rights reserved
*
*=====
*   $Log:$
*=====*/

#include "sfr62.h"           /* include 620 header file */
#include "lcd_exp.h"        /* lcd include file */

/* Setup interrupt routine for INT0
   This must also be setup in the vector table in SECT30.INC */
#pragma INTERRUPT /B INT0_ISR

/* Prototypes */
void Get_Avg (void);
void LCD_write (_far char *, int);

/* Global variables */
unsigned int mem_start = 0x8000; /* declare expanded memory start address */
unsigned char *mem_ptr;          /* declare memory pointer */
unsigned int *word_ptr;         /* declare word memory pointer */
unsigned char ad_on = 0;        /* A/D sampling flag */
unsigned int sample_cnt = 0;    /* sample counter */

union word_define {           /* define word structure */
    struct{
        char    low;          /* low 8 bit */
        char    high;        /* high 8 bit */
    }byte;
    unsigned int word;
} memory;

/* String Messages */
const char msg_text1[] = "Expanded Memory"; /* LCD messages */
const char msg_text2[] = "Demo Program";

```

```

const char msg_ad[] = "A/D Value";
const char msg_avg[] = "A/D Average";

/*****
Name:      Main
Parameters:
Returns:
Description: This is the main program
*****/
void main() {

    int temp;
    unsigned int delay;
    unsigned char ad_data;
    mem_ptr = (unsigned char *) mem_start;

    /* Initialize Ports */
    pd7 = 0xFF;          /* Configure port 7 as all outputs */
    p7 |= 0x80;         /* Initialize port7_4 to 7_7, LEDs off */
    pd8 = 0x02;         /* port 8_1 output */
    p8_1 = 0;           /* Initialize p8_1 (LCD RS) */
    pd10 = 0;           /* A/D input */

    /* Use A/D for reading pot. value */
    adcon0 = 0x00;      /* AN0 ,one shot mode,software trigger,freq /4*/
    adcon1 = 0x20;      /* Set up 8 bit conversion & Vref connected */
    adcon2 = 0x01;      /* Set up sample and hold */

    /* Initialize Timer A4 for S2 switch debounce */
    ta4ic = 0x00;       /* make sure that the interrupt is not active */
    ta4mr = 0x82;       /* set for one shot timer mode */
    ta4 = 0xffff;       /* Debounce time delay */
    ta4s = 1;           /* get ready */
    ta4os = 1;          /* start timer once */

    LCD_init();         /* Initialize LCD display */

    int0ic = 0x05;      /* Enable INT0 interrupt */
    asm("FSET I");      /* Enable all interrupts */

    LCD_write( msg_text1, 1 ); /* Intial LCD message */
    LCD_write( msg_text2, 2 );

    /***** PROGRAM LOOP *****/

    while (1){

        if (ad_on == 1){
            p7_7 = ~p7_7;          /* blink LED to indicate A/D sampling */
            L2homeLCD();           /* Home LCD on line 2 */

            adst = 1;              /* Start A/D conversion */
            while(adst == 1);      /* wait for A/D conversion start bit to
return to 0 */

```

```

    ad_data = ad0;                /* read value from A/D register */
    *mem_ptr = ad_data;           /* save A/D data to memory */
    mem_ptr++;                    /* increment memory pointer */
    sample_cnt++;                /* increment sample counter */

    LCD_DisplayHex(ad_data);      /* Output data to LCD */

    if (sample_cnt >= 0x2000){    /* limit samples to 8k bytes */
        ad_on = 0;               /* stop sampling */
        p7_7 = 1;               /* stop LED blinking */
        Get_Avg ();             /* calculate average A/D value */
    }
}

for (delay=0x2aff; delay>0; delay--); /* sampling delay ~100ms */
}
}
/***** END OF MAIN *****/

/*****
Name:          INTO_ISR
Parameters:
Returns:
Description:   INTO interrupt routine, S2 is connected to INTO
              S2 controls when A/D sampling starts and stops
*****/
void INTO_ISR(void)
{
    if (ir_ta4ic == 0)           /* Switch Debounce timer timeout?
*/
        return;                 /* If not return, do
nothing */

    int0ic = 0x00;              /* disable INTO interrupt
*/

    /* Start A/D sampling */
    if(ad_on == 0){             /* A/D sampling currently
off?*/
        ad_on = 1;              /* turn on */
        mem_ptr = (unsigned char *) mem_start; /* Reset memory to begining
*/

        sample_cnt = 0;         /* Reset sample counter */
        clrLCD ();             /* clear LCD */
        LCD_write( msg_ad, 1 ); /* change LCD display */
    }

    /* Stop A/D sampling */
    else if (ad_on == 1){      /* A/D sampling currently on ? */
        ad_on = 0;             /* turn off */
        p7_7 = 1;              /* stop LED blinking */
        Get_Avg ();            /* calculate average A/D value */
}
}

```

```

    }

    ir_ta4ic = 0;          /* reset debounce timer */
    ta4os = 1;           /* start debounce timer */
    int0ic = 0x05;       /* Enable INT0 interrupt */
}

/*****
Name:      Get_Avg
Parameters:
Returns:
Description: Read A/D data from external memory and calculate average
*****/
void Get_Avg (void)
{
    unsigned long int total = 0;    /* declare variables */
    unsigned int avg = 0;
    int count;

    clrLCD ();                    /* clear LCD */
    LCD_write( msg_avg, 1 );       /* change LCD display */
    L2homeLCD();                  /* Home LCD on line 2 */

    count = sample_cnt;           /* get number of samples */
    word_ptr = (unsigned int *) mem_start; /* Reset memory to beginning */

    for (total = 0; count > 1; count -= 2){
        memory.word = *word_ptr;   /* read word from memory */
        total += memory.byte.low;   /* add lower byte to total */
        total += memory.byte.high; /* add upper byte to total */
        word_ptr ++;               /* increment word memory pointer */
    }

    if(count == 1){               /*if odd number of data,get last one*/
        memory.word = *word_ptr;   /* read word from memory */
        total += memory.byte.low;   /* add lower byte to total */
        count --;
    }

    avg = total / sample_cnt;     /* calculate average value */

    LCD_DisplayHex(avg);         /* Output average to LCD */
}

/*****
Name:      LCD_write
Parameters:
Returns:
Description: This routine outputs some text to the LCD display
*****/
void LCD_write ( _far char * data_string, int line )
{
    int p;

    if(line == 1)

```

```
        L1homeLCD();                /* home display on line 1*/  
else  
        L2homeLCD();                /* home display on line 2*/  
  
for (p=0; data_string[p]; p++){    /* This loop reads in the text string */  
        SendChar(data_string[p]);  
}  
}
```

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