## Renesns

## Converting between Analog and Digital Domains

Chapter 6

Renesas Electronics America Inc.
Advanced Embedded Systems using the RX63N

Rev. 0. 1

## Topics

■ Need
■ Reference voltage

- Resolution
- Sample and Hold circuit
- Successive approximation
- Transfer function

■ Conversion speed
■ 12-bit ADC registers

- Operating modes
- 10-bit ADC registers
- D/A converter

■ D/A converter registers

## Need

- The microcontroller can process only digital data
- Are the following commonly measured quantities analog or digital?

1. Distance
2. Weight
3. Acceleration
4. Temperature

## Need

- All physical quantities are analog. The world is analog !
- We need to convert these analog values to digital for the microcontroller to comprehend the value of the real analog physical quantity


## Reference voltage

- The analog value is compared with a known reference voltage to obtain its digital form
- The measurement process is called quantization



## Resolution

- The number of bits in the digital output is called the resolution of the ADC
- A 10-bit A/D convertor can produce $2^{\wedge} 10=1024$ distinct digital outputs
- RX63N microcontroller has an 8 channel 10-bit and a 21 channel 12-bit A/D converter units


## Sample and Hold circuit

- This circuit catches hold of the voltage to be converted to digital form
- It is helpful particularly when the input analog voltage varies very fast
- When the switch is closed, the capacitor charges to the value of analog voltage and that value is fed to the A/D converter

Sampling Switch


## Successive Approximation

- RX63N microcontroller employs this method of conversion
- In this method, initially the microcontroller compares the analog voltage with half the reference voltage
- In each approximation step, the microcontroller halves the possible range between which the digital value lies
- In this way the microcontroller closes in on the analog value, setting 1 or 0 to the bit position starting from MSb
- Set 1 if the analog value is greater than the reference value of that step, else set to 0


## Successive Approximation

- Consider 2.5 V to be measured with Vref=3.3V using 10bit A/D converter
- First 2.5 is compared with 1.65 (mean of $0 \& 3.3$ ). Since $2.5>1.65$, our digital value is $1 \times x x x x x x x x$
- Next compare 2.5 with 2.47 (mean of $1.65 \& 3.3$ ) . Since $2.5>2.47$, our digital value is $11 x x x x x x x x$
- We proceed in similar way till we get the Isb of the digital form
- We compare ' $n$ ' times, where ' $n$ ' is the resolution of the A/D converter



## Transfer function

- $\mathrm{n}=$ digital output

■ Vin = input analog voltage

- V+ref = upper reference voltage

■ V-ref = lower reference voltage, generally zero
■ $\mathrm{N}=$ resolution of $\mathrm{A} / \mathrm{D}$ converter

$$
n=\left[\frac{\left(V_{\mathrm{in}}-V_{-\mathrm{ref}}\right)\left(2^{N}-1\right)}{V_{+\mathrm{ref}}-V_{-\mathrm{ref}}}+\frac{1}{2}\right] \text { int }
$$

## Conversion speed

■ Conversion speed $=$ Start delay(tD) + input sampling
time(tSPL) + conversion time (tSAM)

tD: A/D conversion start delay time
tSPL: Input sampling time
tSAM: Successive conversion time
tCONV: A/D conversion time

## 12-bit ADC registers

Some of the important registers are:

■ A/D Data Registers (ADDRn) ( $\mathrm{n}=0$ to 20)

- 16-bit register
- Holds the digital value

To use a particular channel, the respective port has to be set up as input. For example, to use ANO, port 4 pin 0 use: PORT4.PDR.BIT.B0 = 0;

For inputs, the Port Mode Register (PMR) also has to set up.
This can be done using:
PORT4.PMR.BIT.B0 = 1;

## 12-bit ADC registers

■ A/D Control Register (ADCSR)

- Start conversion control
- Mode select
- Interrupt enable
- A/D clock speed

Address: 0008 9000h


## 12-bit ADC registers

-A/D Channel Select Register (ADANSx ( $\mathrm{x}=0$ or 1 ) )

- 2 registers to select 20 channels



## Operating modes

- Single cycle scan

Performs conversion on single or multiple channels once

■ Continuous scan mode
Performs continuous conversion on single or multiple channels

## ADC Initialization

```
1. void ADC_Init(){
2. SYSTEM.MSTPCRA.BIT.MSTPA17 = 0;
3. S12AD.ADCSR.BYTE = 0x0C;
4. S12AD.ADANS0.WORD = 0x01;
5. S12AD.ADCER.BIT.ACE = 1;
6. S12AD.ADCER.BIT.ADRFMT = 0;
7. }
```

Line 2: 12-bit ADC has been selected using the Module Stop Control Register A.
Line 3: the Control Register is set: software trigger has been enabled ( $b 1=0, b 0=0$ ), the PCLK ( $b 3=1, b 2=1$ ) has been selected, A/D Interrupt Enable has not been enabled (b4=0) and Single-Cycle Scan mode has been selected ( $b 6=0$ ).
Line 4: Channel 0 (ANOOO) has been selected.
Line 5: automatic clearing of ADDRn
Line 6: right alignment of ADDRn is done.

## Example of a ADC Initialization

```
    1. void ADC_Init() {
    2. PORT4.PDR.BIT.B0 = 0;
    3. PORT4.PMR.BIT.B0 = 1;
    4. SYSTEM.MSTPCRA.BIT.MSTPA17 = 0;
    5. S12AD.ADCSR.BYTE = 0x0C;
    6. S12AD.ADANS0.WORD = 0x01;
    7. S12AD.ADCER.BIT.ACE = 1;
    8. S12AD.ADCER.BIT.ADRFMT = 0;
    9. S12AD.ADSTRGR.BIT.ADSTRS = 0x0;
    10. S12AD.ADCSR.BIT.ADST = 1;
11. }
```

What does each line do?

## Using ADC data

```
12. while(1){
13. if(S12AD.ADCSR.BIT.ADST == 0 && i == 0){
14. ADC_out = S12AD.ADDR0 & 0X0FFF;
15. sprintf(ADC_OUT,"%d",ADC_out);
16. lcd_display(LCD_LINE2,ADC_OUT );
17. i++;
18. }
19. }
```

What will this code do?

## In Class Exercise

How would you initialize the ADC and read the internal temperature sensor?

1. void ADC_Init() \{
2. 
3. 
4. 
5. 
6. 
7. 
8. 
9. 
10. 
11. \}

## 10-bit ADC registers

Some of the important registers are:

- A/D Data Register (ADDRn) ( $\mathrm{n}=\mathrm{A}$ to H )
- 16-bit register
- Holds the digital data


## 10-bit ADC registers

- A/D Control/Status Register (ADCSR)
- Select the input channels
- Start or stop A/D conversion
- Enable or disable ADI interrupt


## 10-bit ADC registers

- A/D Control Register (ADCR)
- Type of A/D conversion mode
- Clock select
- Trigger select

Value after reset:



## D/ A converter

- It converts a digital value stated by programmer to corresponding analog voltage on a microcontroller pin
- It may be needed for controlling other devices like motor
- RX63N has a 10-bit D/A converter which has 2 channels
- Analog value $=(\mathrm{D} / \mathrm{A}$ data register value / 1024) * Vref


## D/ A converter registers

Some of the important registers are:

- D/A Data Register (DADRm) $(m=0,1)$
- 16-bit registers
- Holds the digital value to be converted to analog voltage


## D/ A converter registers

- D/A Control Register (DACR)
- Channel select
- Enable or disable D/A converter unit

|  | b7 | b6 | b5 | b4 | b3 | b2 | b1 | bo |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | DAOE1 | DAOE 0 | DAE | - | - | - | - | - |
| Value after reset: | 0 | 0 | 0 | 0 | 0 | 0 | 0 | 0 |

## Example of using the DAC

```
1. #include "iodefine.h"
2. void DAC_Init();
3. void main(void){
4. PORT0.PDR.BIT.B5 = 1;
5. PORT0.PMR.BIT.B5 = 0;
6. DAC_Init();
7. while(1){}
8. }
9.
10. void DAC_Init(){
11. SYSTEM.MSTPCRA.BIT.MSTPA19 = 0;
12. DA.DADR1 = 102;
13. DA.DACR.BYTE = 0x9F;
14. }
```


## Conclusion

- We covered the A/D conversion concepts like transfer function, resolution, successive approximation technique
- The important control registers were also discussed

■ You can now set A/D converter and D/A converter of RX63N to be used in your program

## References

All images taken from:
[1] Renesas Electronics, Inc., RX63N Group, RX631 Group User's Manual: Hardware, Rev 1.60, February 2013

## Renesas

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