

Deep Learning for Image Instance Segmentation ----RefineNet

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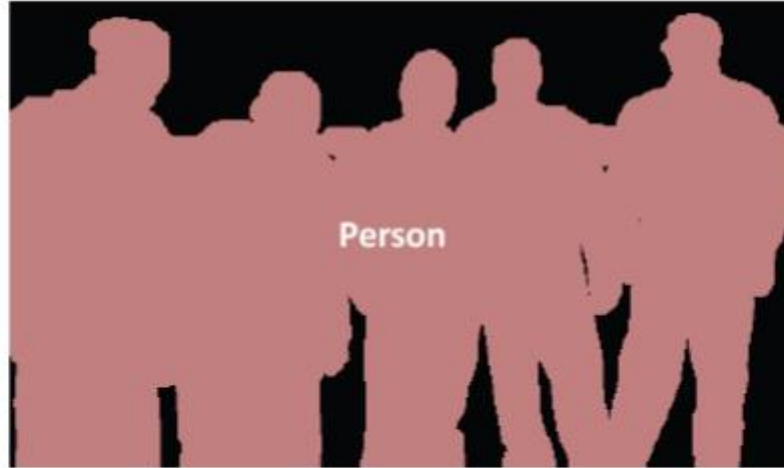
Course Website:

<http://webpages.uncc.edu/jfan/itcs5152.html>

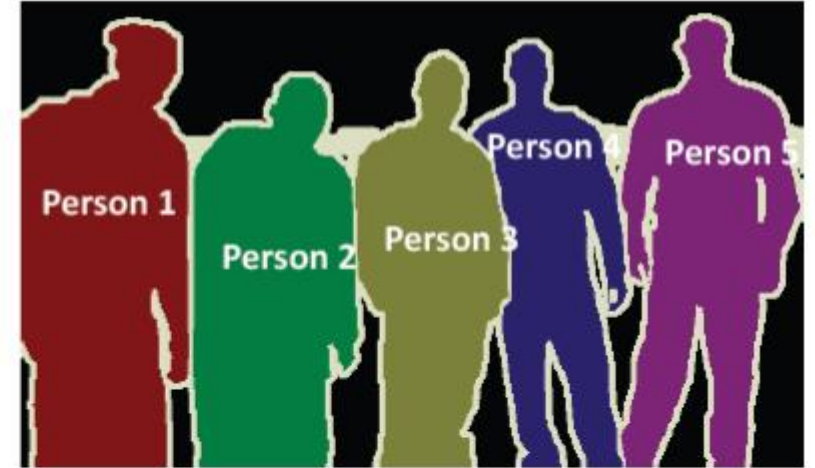
Definition of Image Instance Segmentation



Object Detection



Semantic Segmentation



Instance Segmentation

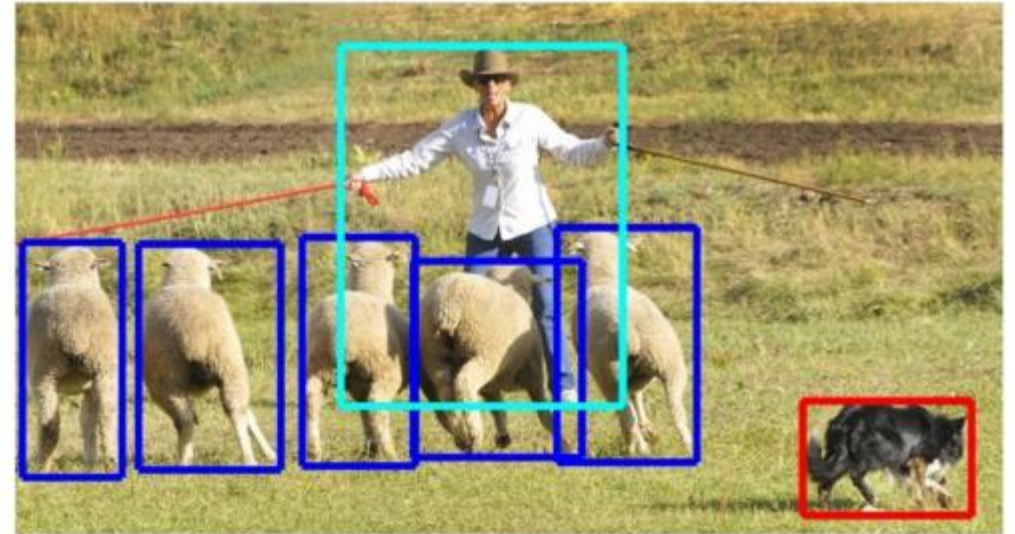


Instance segmentation = object detection + semantic segmentation?

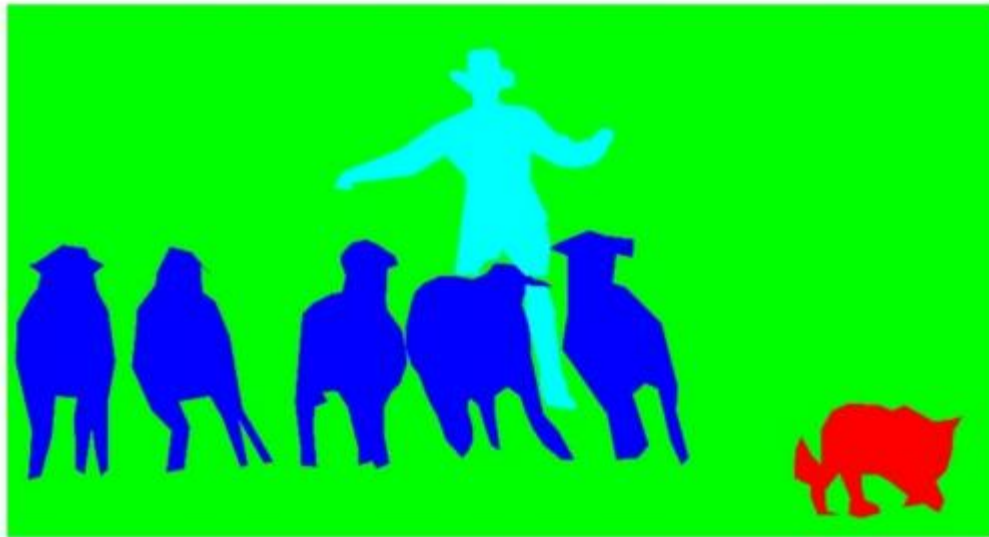
Scene understanding



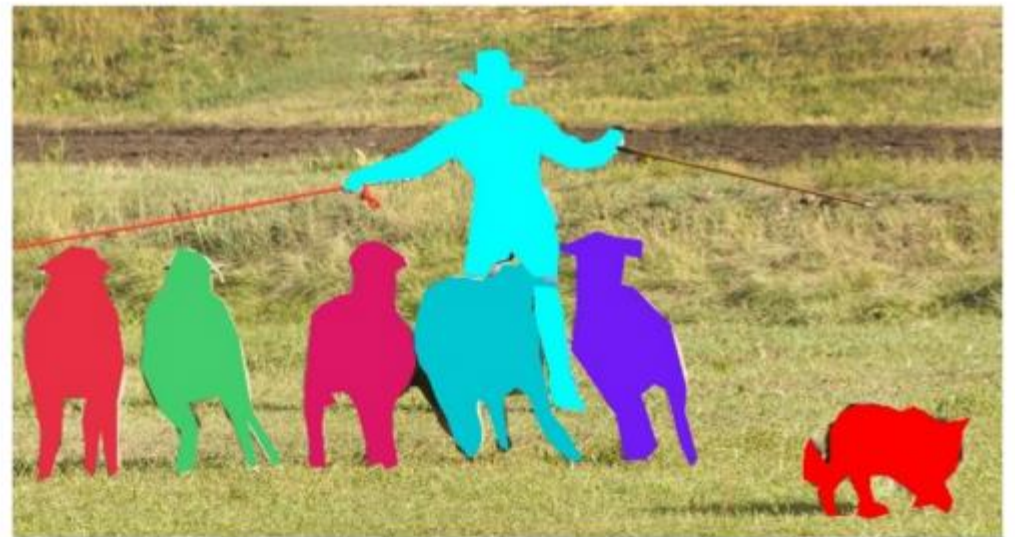
Image classification



Object detection



Semantic segmentation



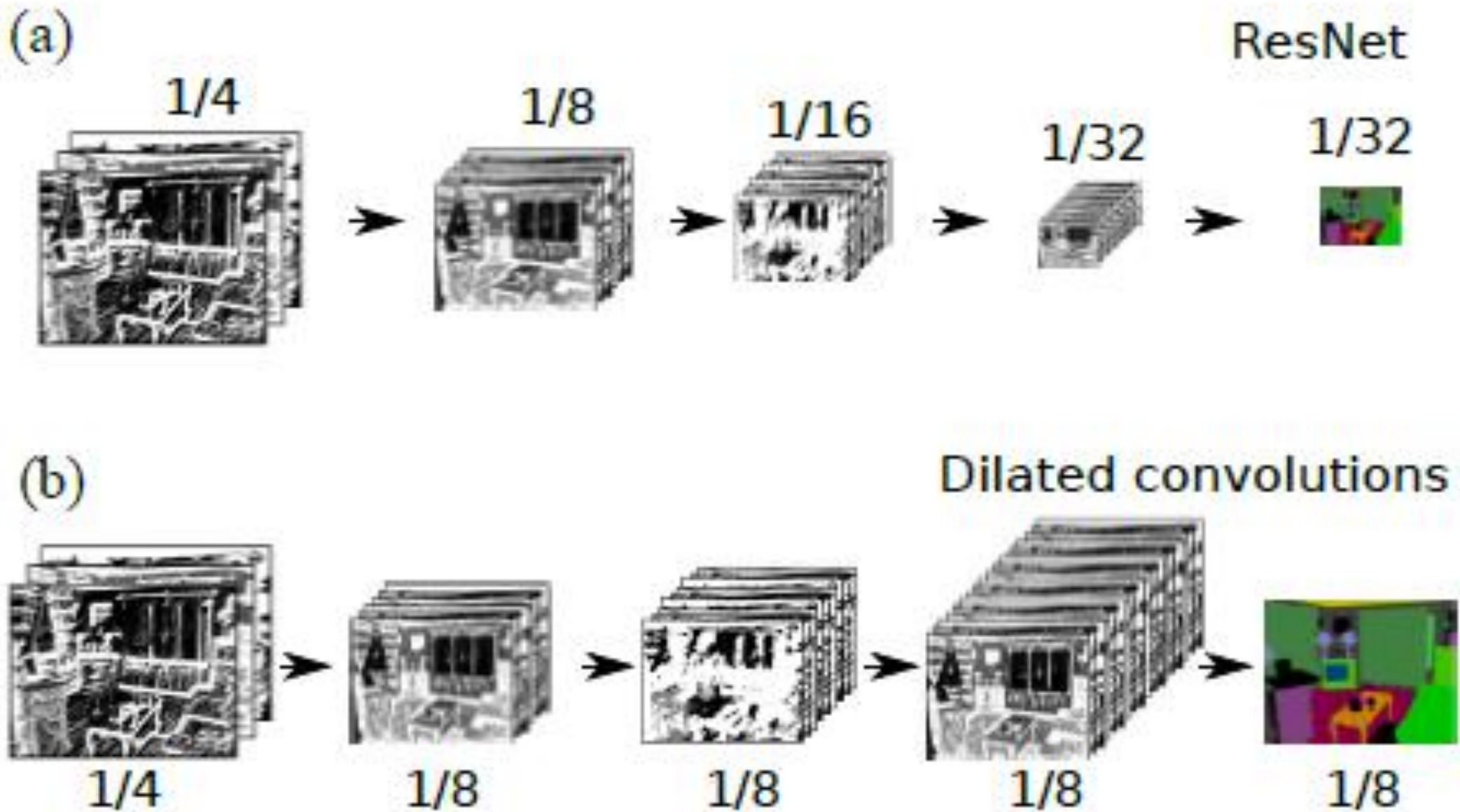
Instance segmentation

Instance-level Object Understanding Today

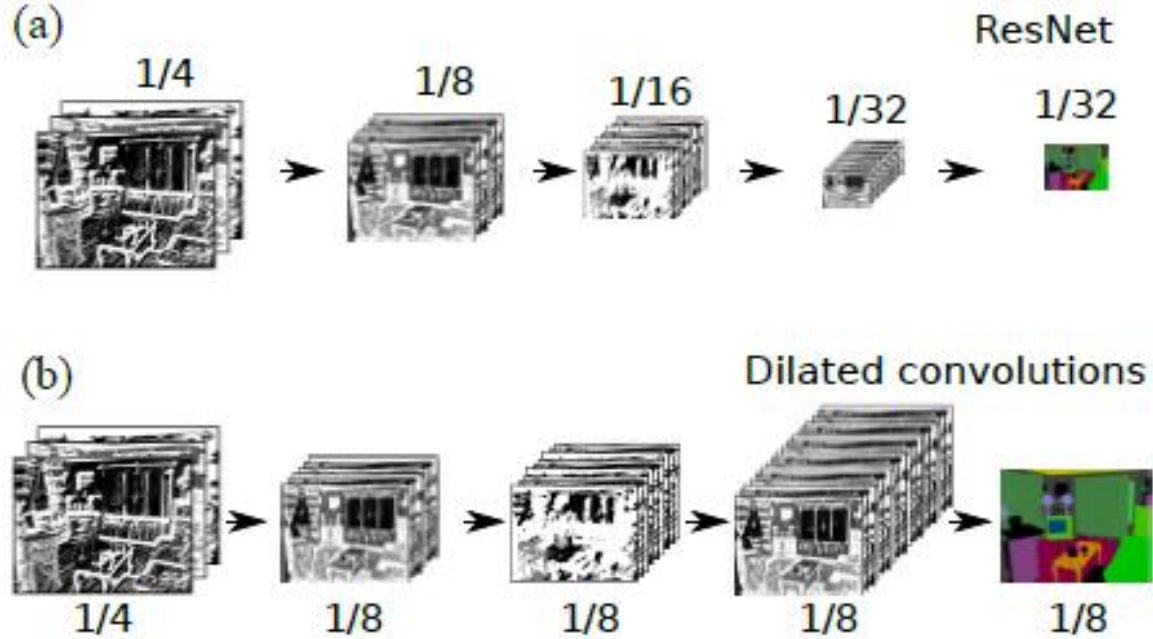


He, Gkioxari, Dollár, Girshick. Mask R-CNN. In ICCV 2017

Problems of ResNet and Dilated Convolution



Problems of ResNet and Dilated Convolution



ResNet:

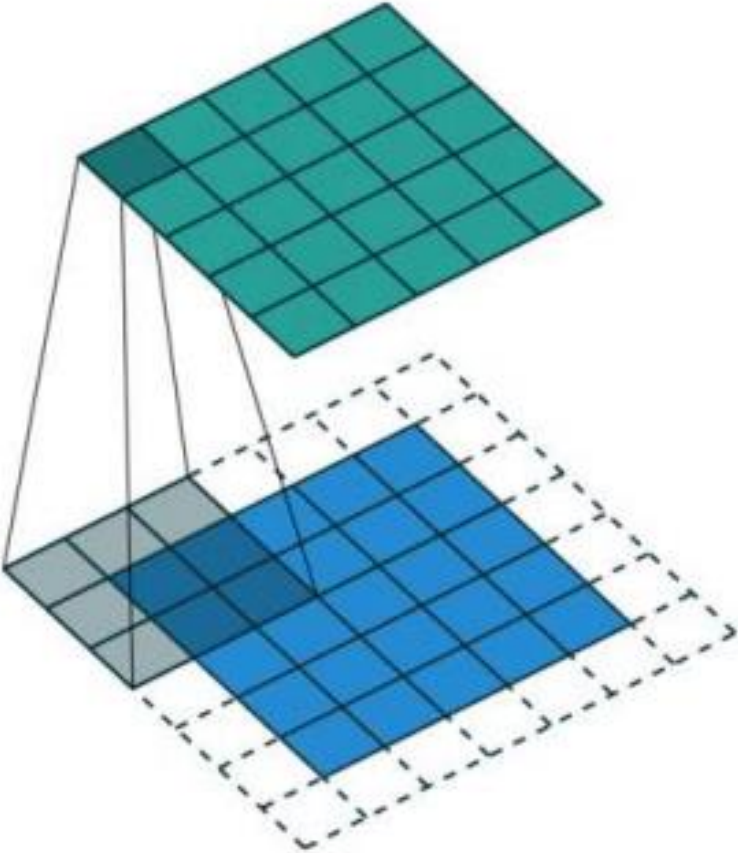
It suffers from **downscaling** of the feature maps which is not good for semantic segmentation.

Dilated (Atrous) Convolution:

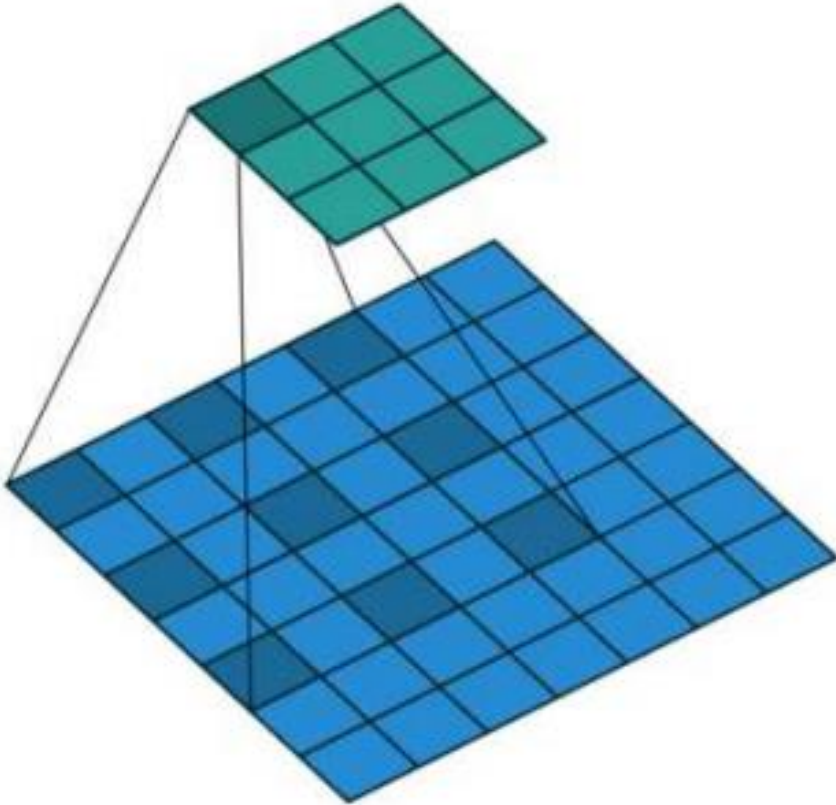
It can help to keep the resolution of output feature maps larger, atrous filters are **computationally expensive to train** and quickly reach memory limits even on modern GPUs.

Problems of ResNet and Dilated Convolution

Convolution



Dilated Convolution

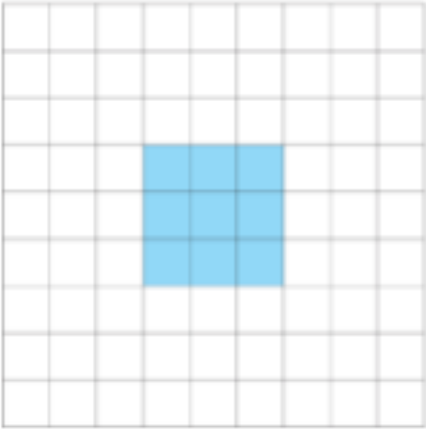


Problems of ResNet and Dilated Convolution

Atrous Convolution

- Small field of view cause **accurate localization**
- Large field of view cause to **context assimilation**

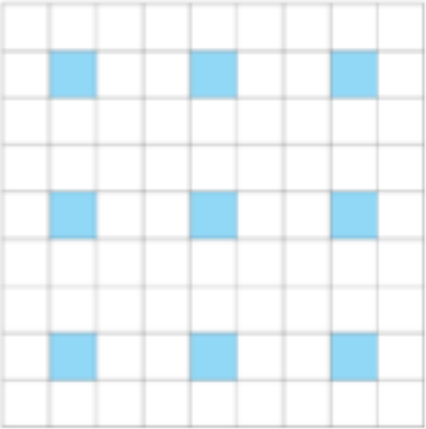
rate = 1



rate = 2

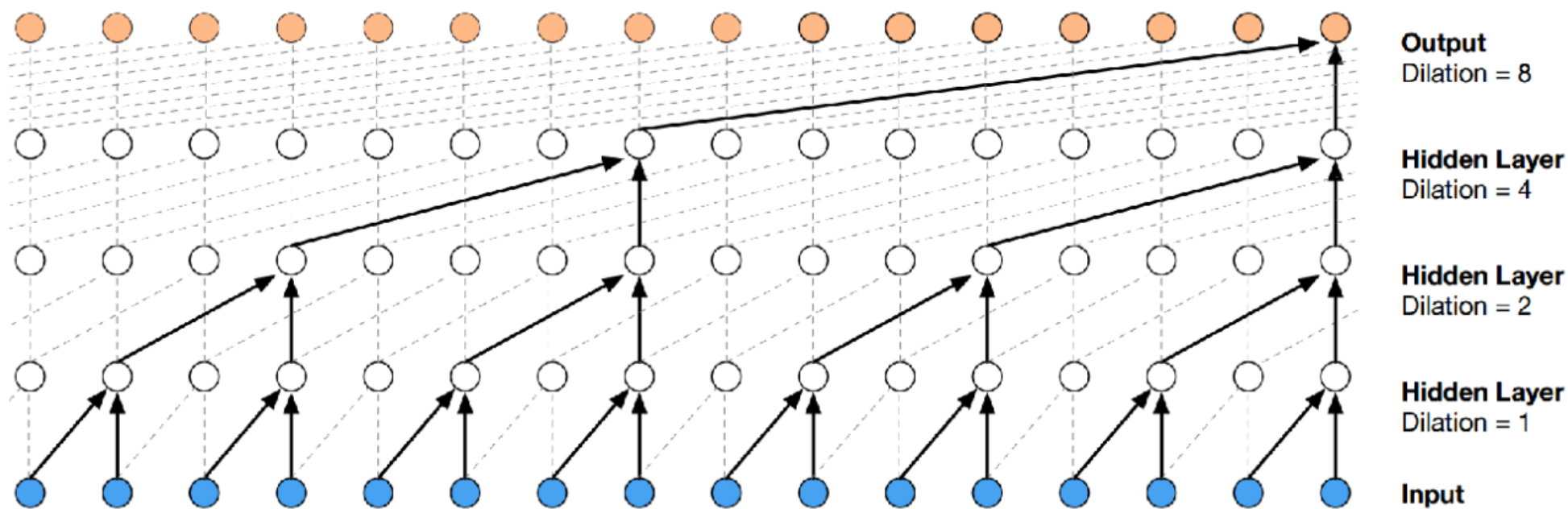


rate = 3



Dilated convolutions

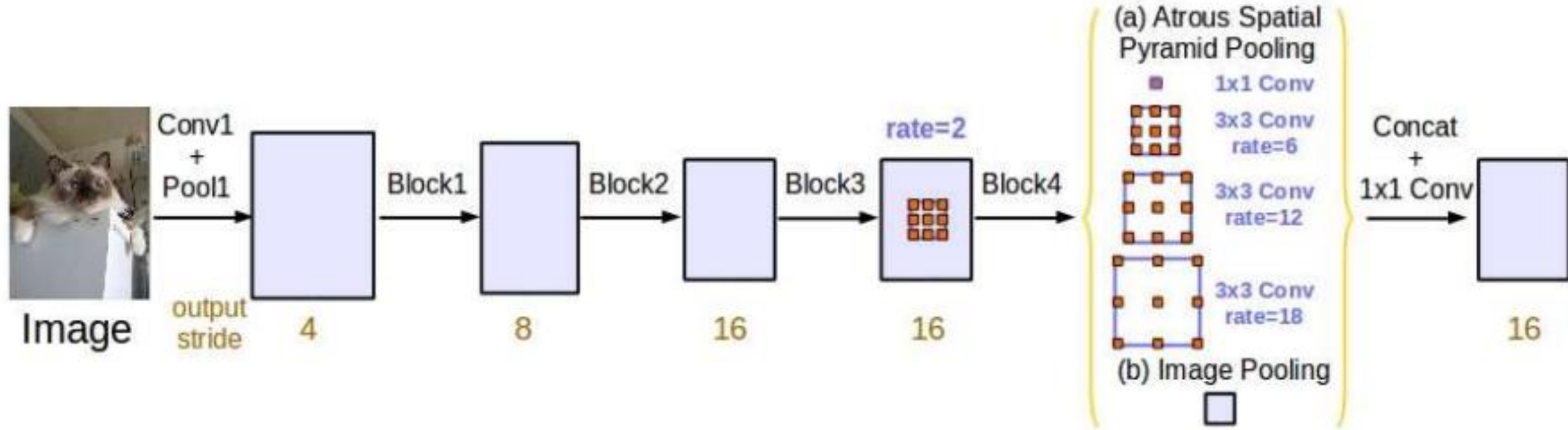
- “Multi-Scale Context Aggregation by Dilated Convolutions”, Fisher Yu, Vladlen Koltun, **23 Nov, 2015**
- a.k.a stroud convolution, convolution with holes
- Enlarge the size of receptive field without losing resolution



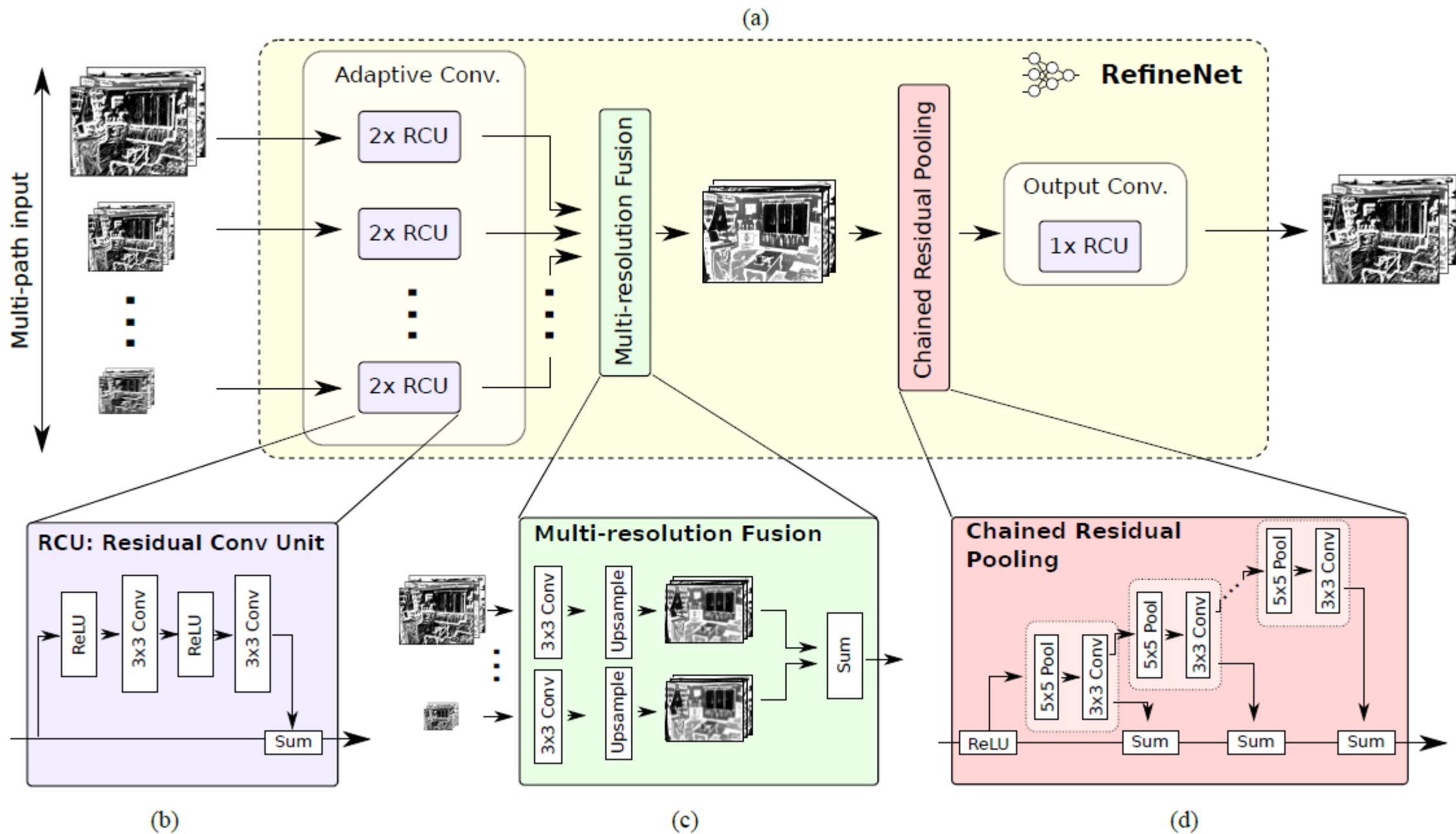
The figure is from “WaveNet: A Generative Model for Raw Audio”

Problems of ResNet and Dilated Convolution

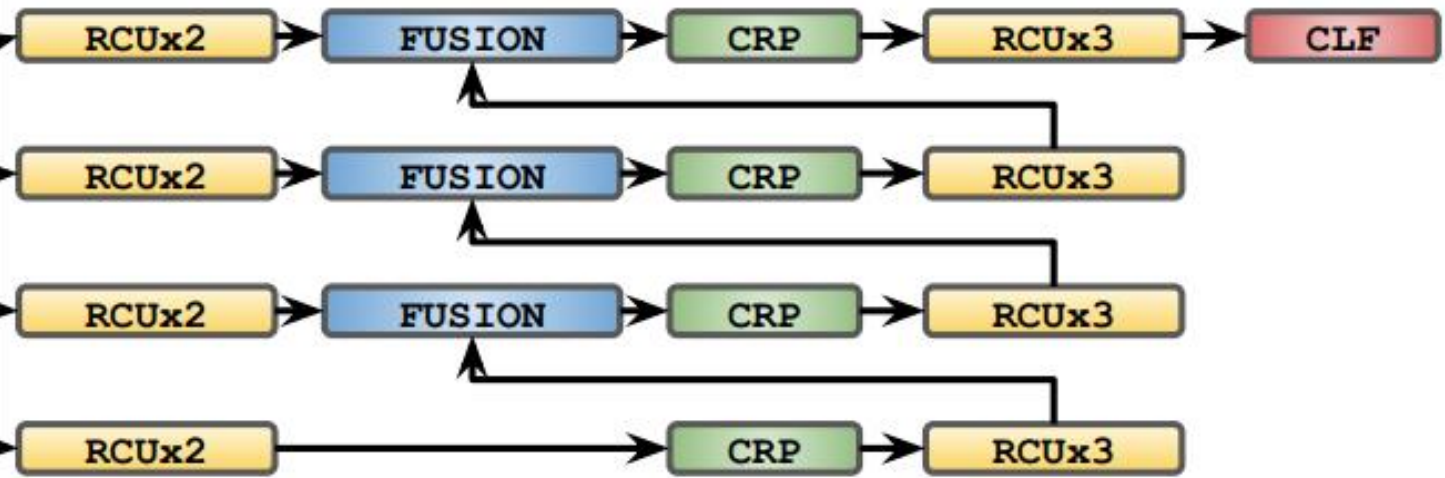
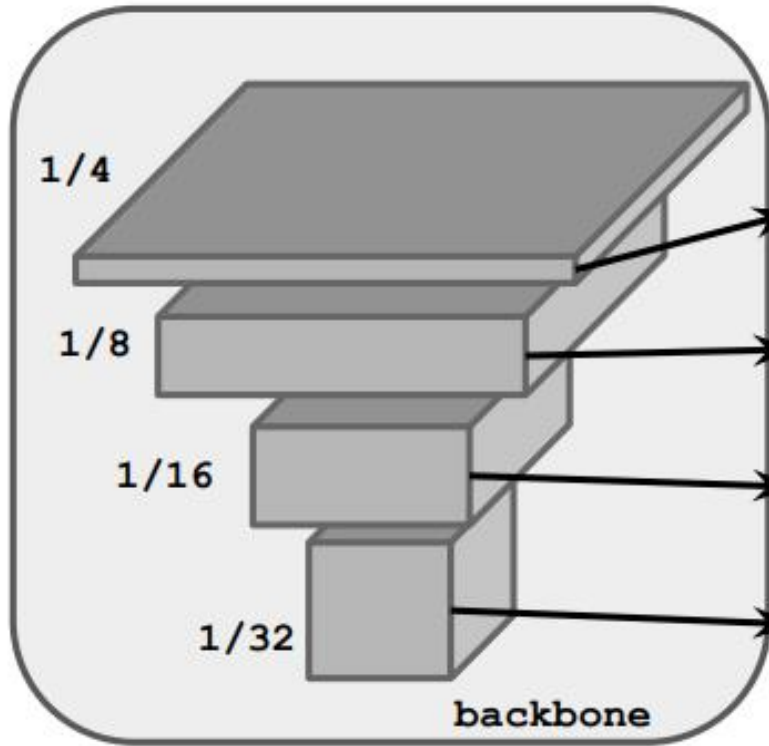
DeepLab v3 Architecture



RefineNet



RefineNet



Overall Architecture of RefineNet

RefineNet uses the [ResNet](#) as the backbone. Along the [ResNet](#), different resolutions of feature maps go through **Residual Conv Unit** (RCU). [Pre-Activation ResNet](#) is used.

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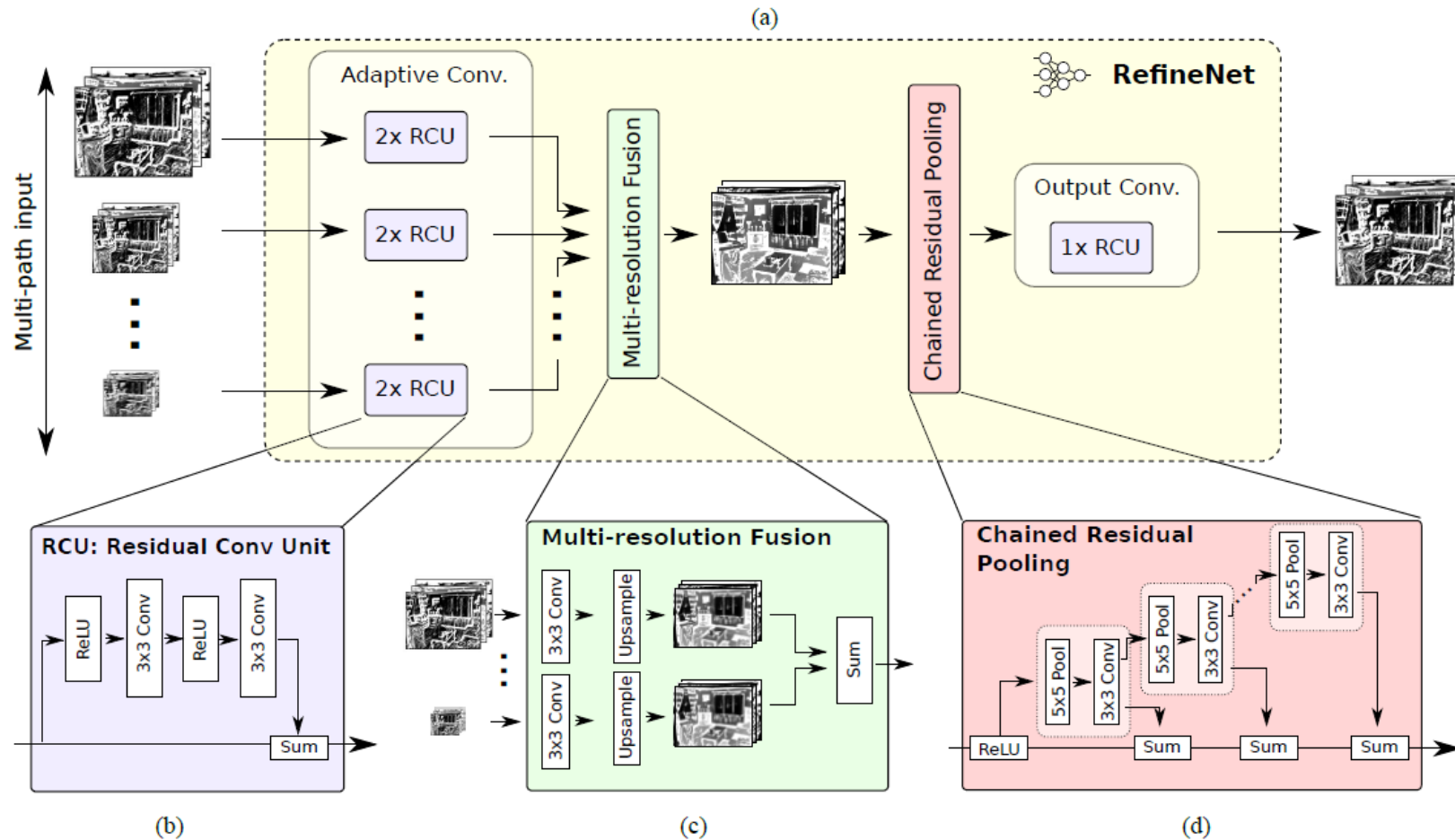
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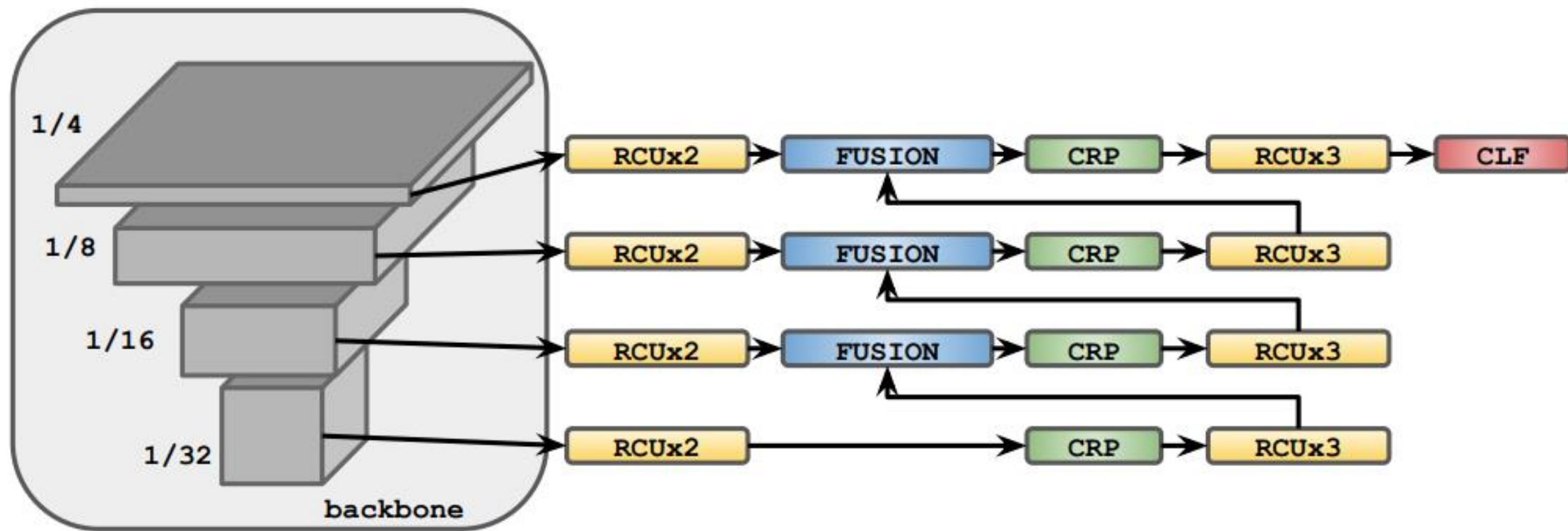
Chained Residual Pooling: The output feature maps of all pooling blocks are fused together with the input feature map through summation of residual connections. It **aims to capture background context from a large image region**.

Overall Architecture of RefineNet

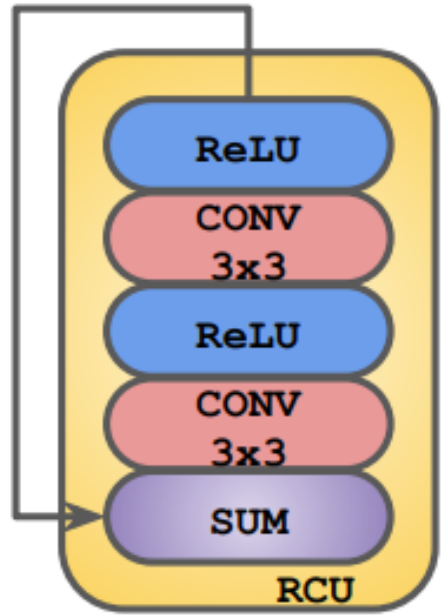
Output Conv: Another RCU is placed to employ non-linearity operations on the multi-path fused feature maps to generate features for further processing or for final prediction.



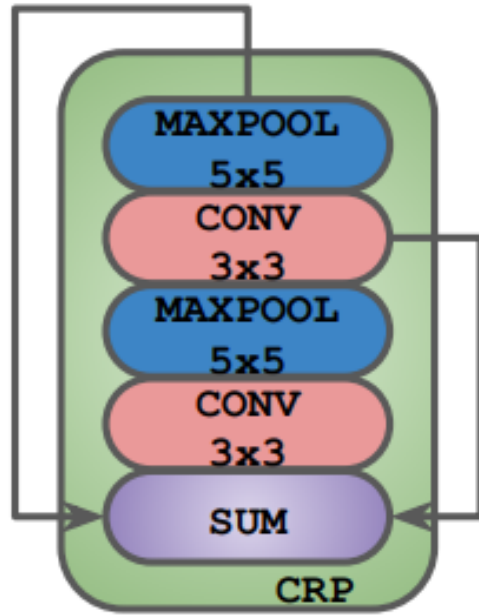
Overall Architecture of RefineNet



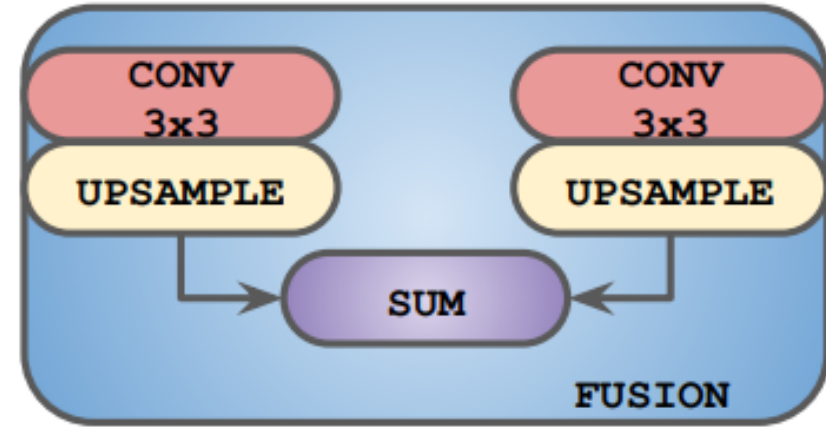
Overall Architecture of RefineNet



(b)



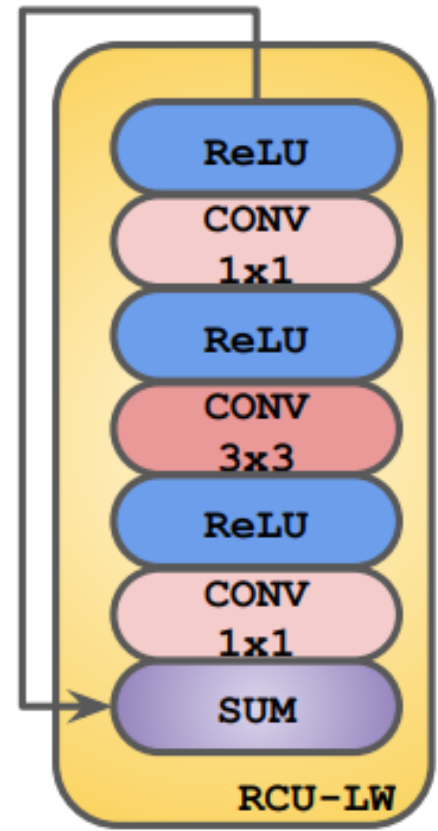
(c)



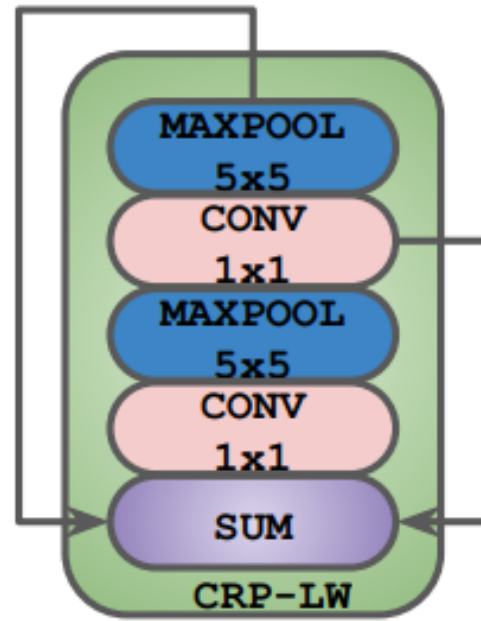
(d)

(b)-(d) general outline of original RCU, CRP and fusion blocks

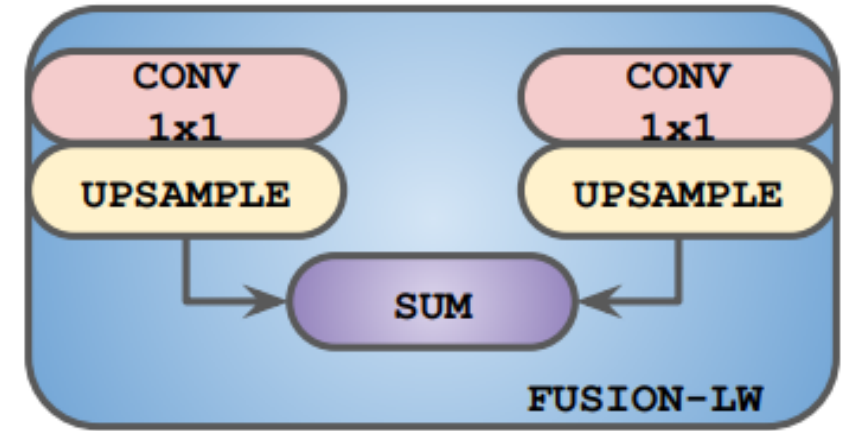
Overall Architecture of RefineNet



(e)



(f)

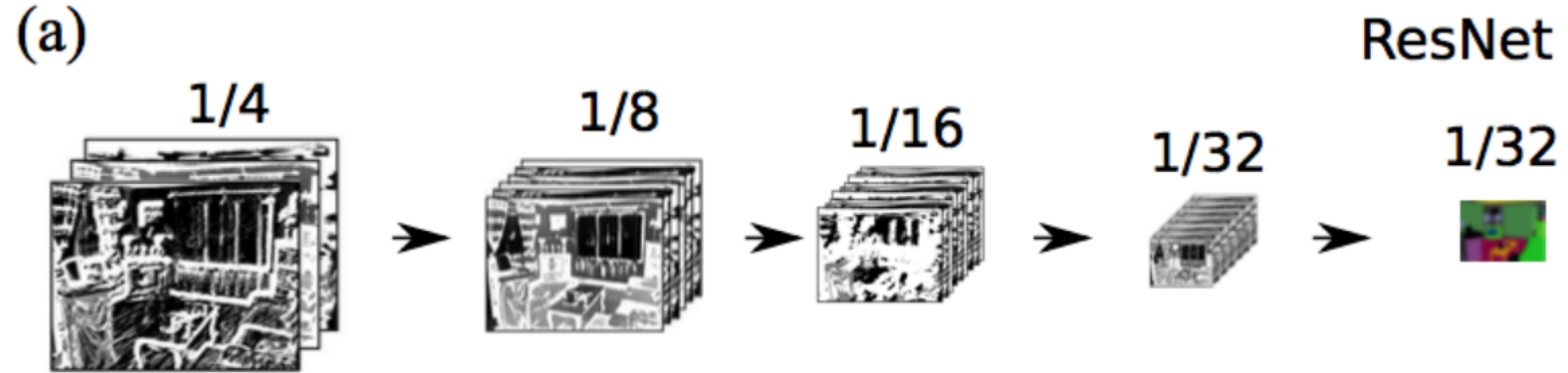


(g)

(e)-(g) light-weight RCU, CRP and fusion blocks. In the interests of brevity, we only visualize 2 convolutional layers for the CRP blocks (instead of 4 used in the original architecture).

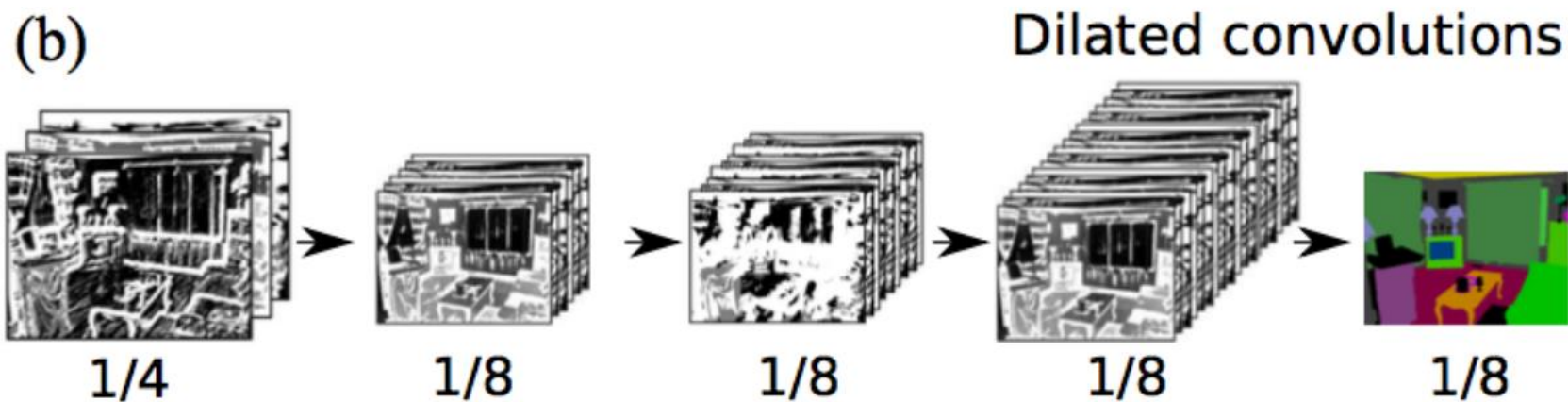
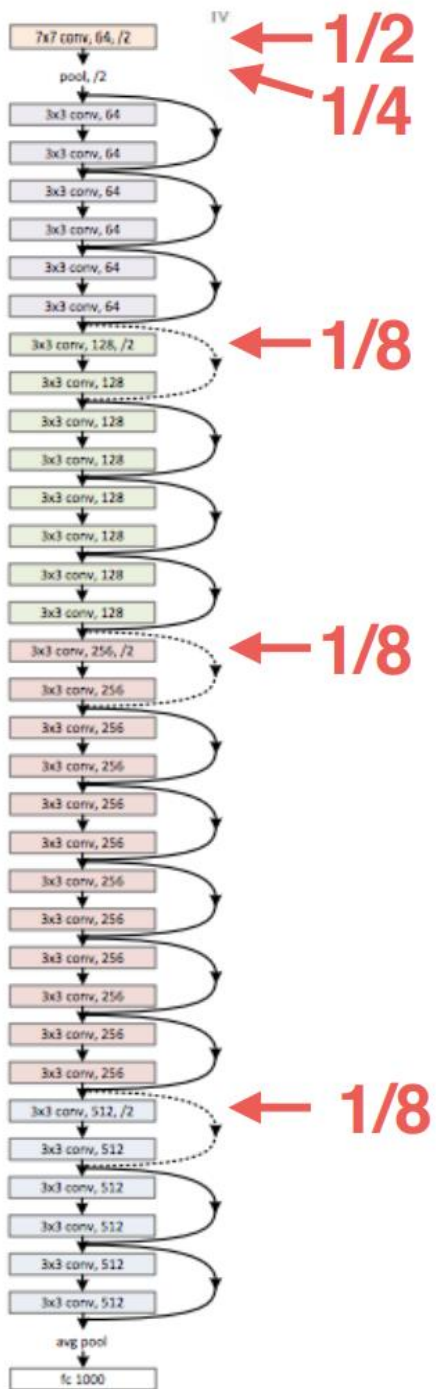
Dilated convolutions

- For example, the feature maps of ResNet are downsampled 5 times, and 4 times in the 5 are done by convolutions with stride of 2 (only the first one is by pooling with stride of 2)

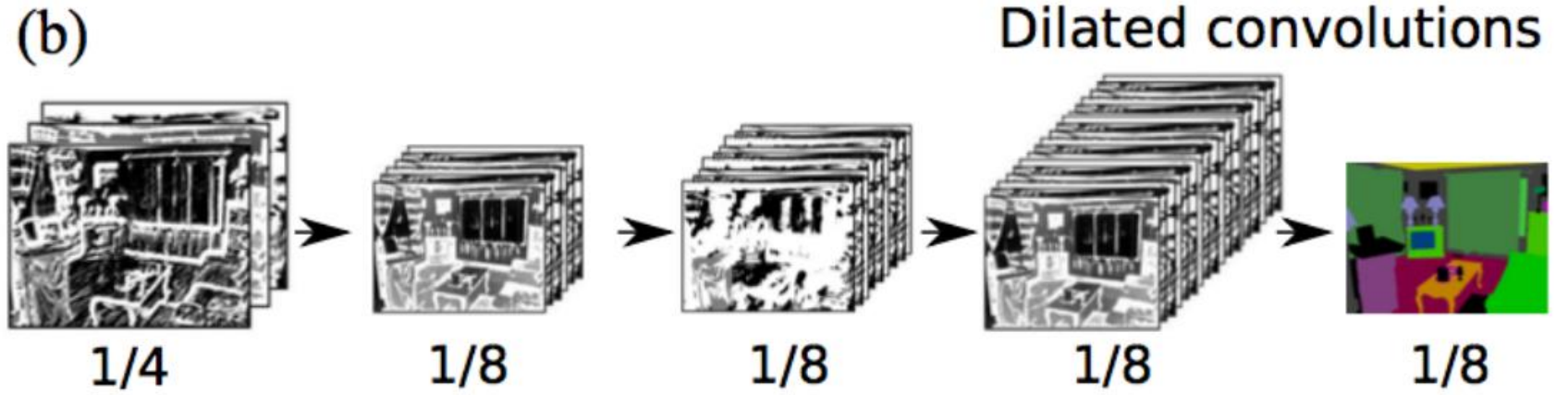
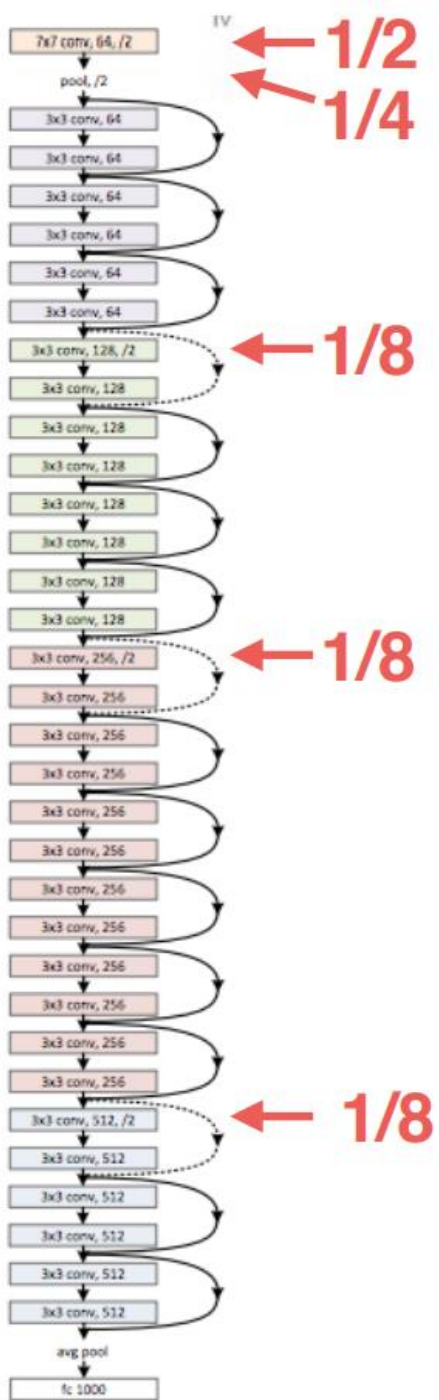


Dilated convolutions

- By using dilated convolutions instead of vanilla convolutions, the resolution after the first pooling can be kept as the same to the end



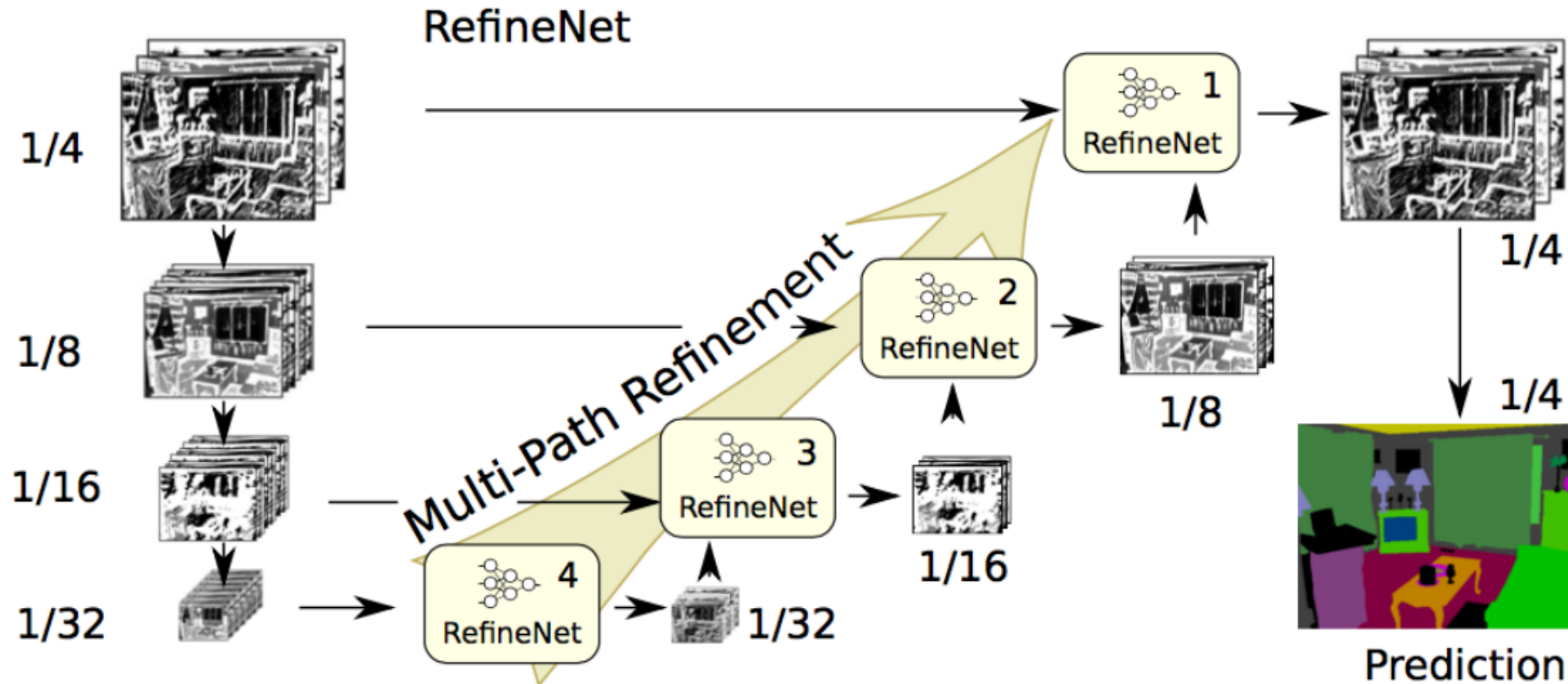
Dilated convolutions



But, it is still 1/8...

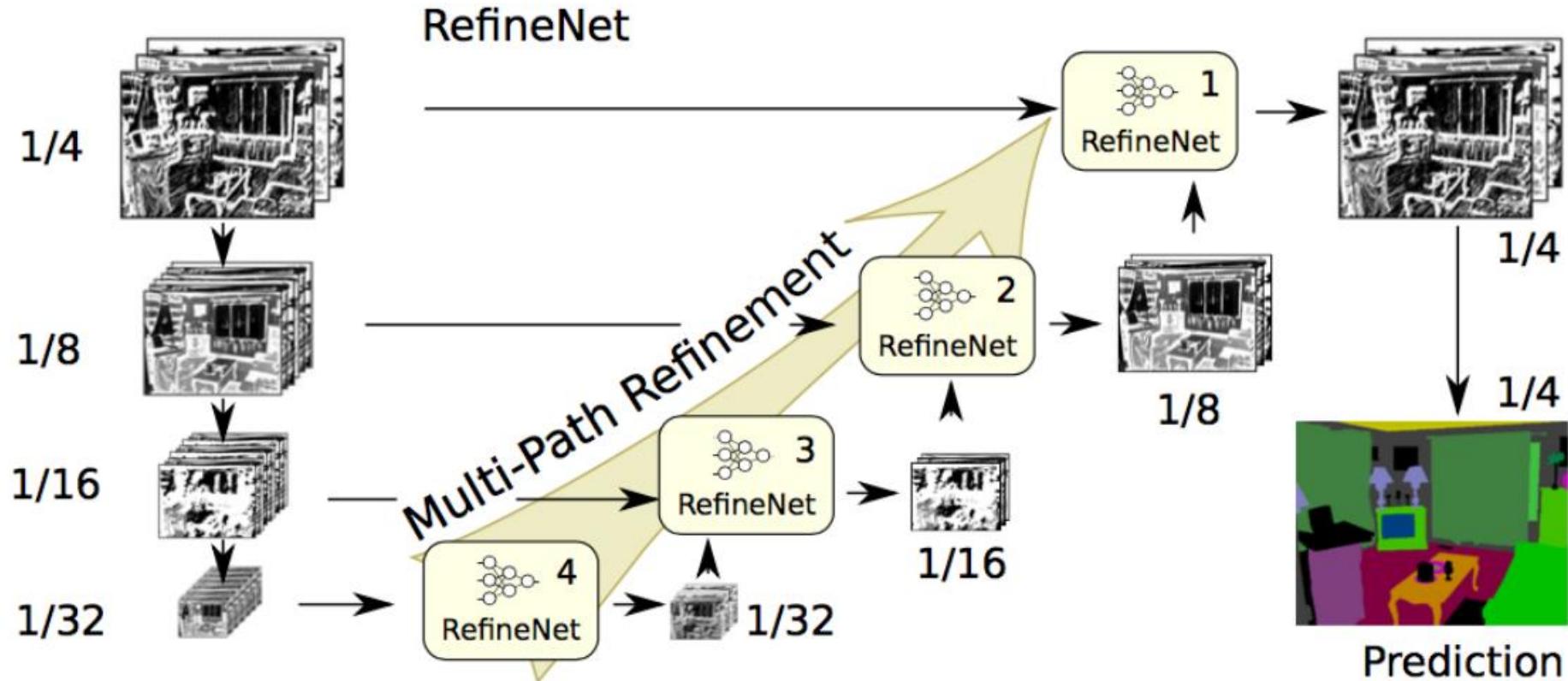
RefineNet

- “RefineNet: Multi-Path Refinement Networks for High-Resolution Semantic Segmentation”, Guosheng Lin, Anton Milan, Chunhua Shen, Ian Reid, **20 Nov. 2016**

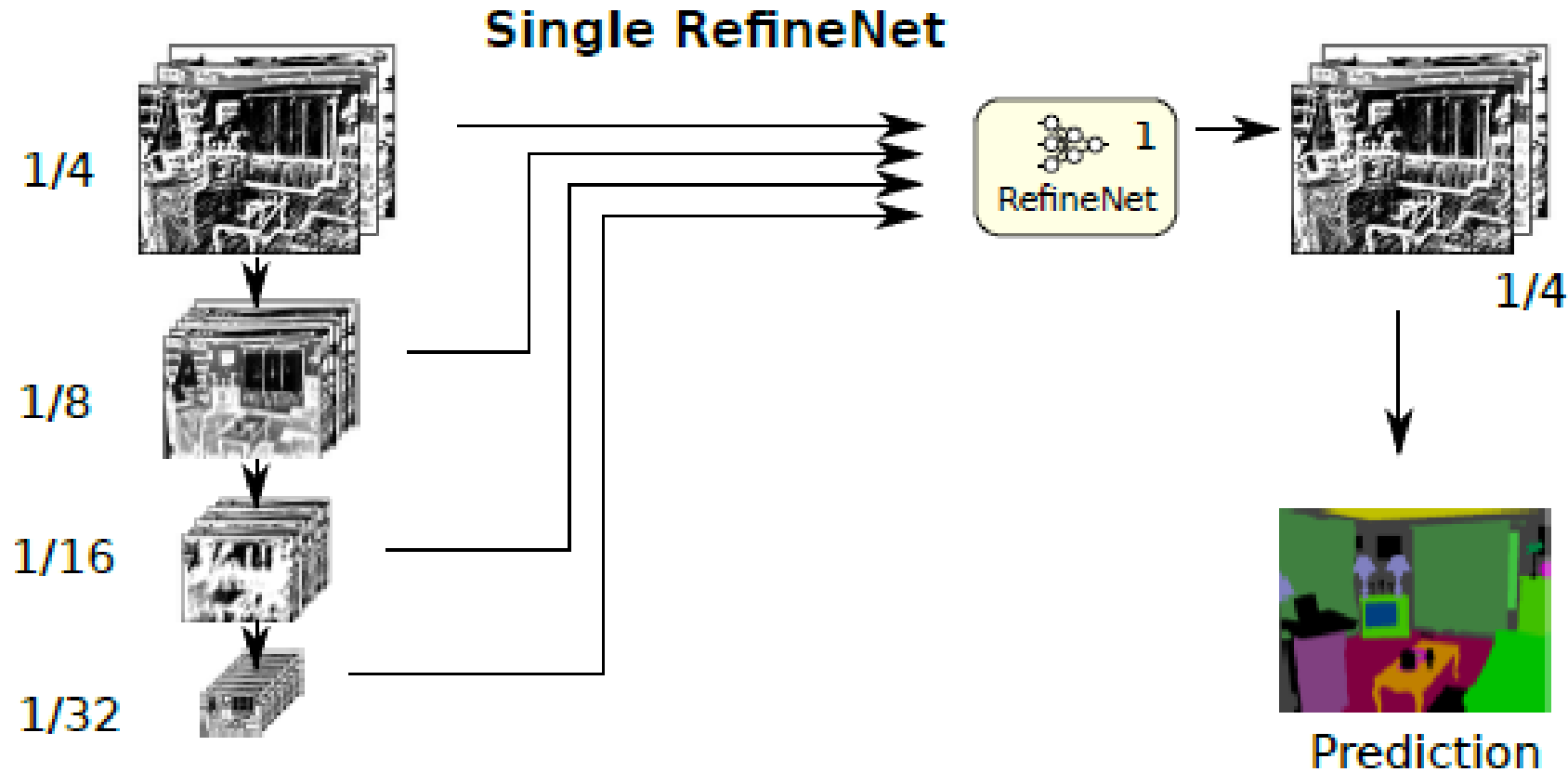


RefineNet

- Each intermediate feature map is refined through “RefineNet module”



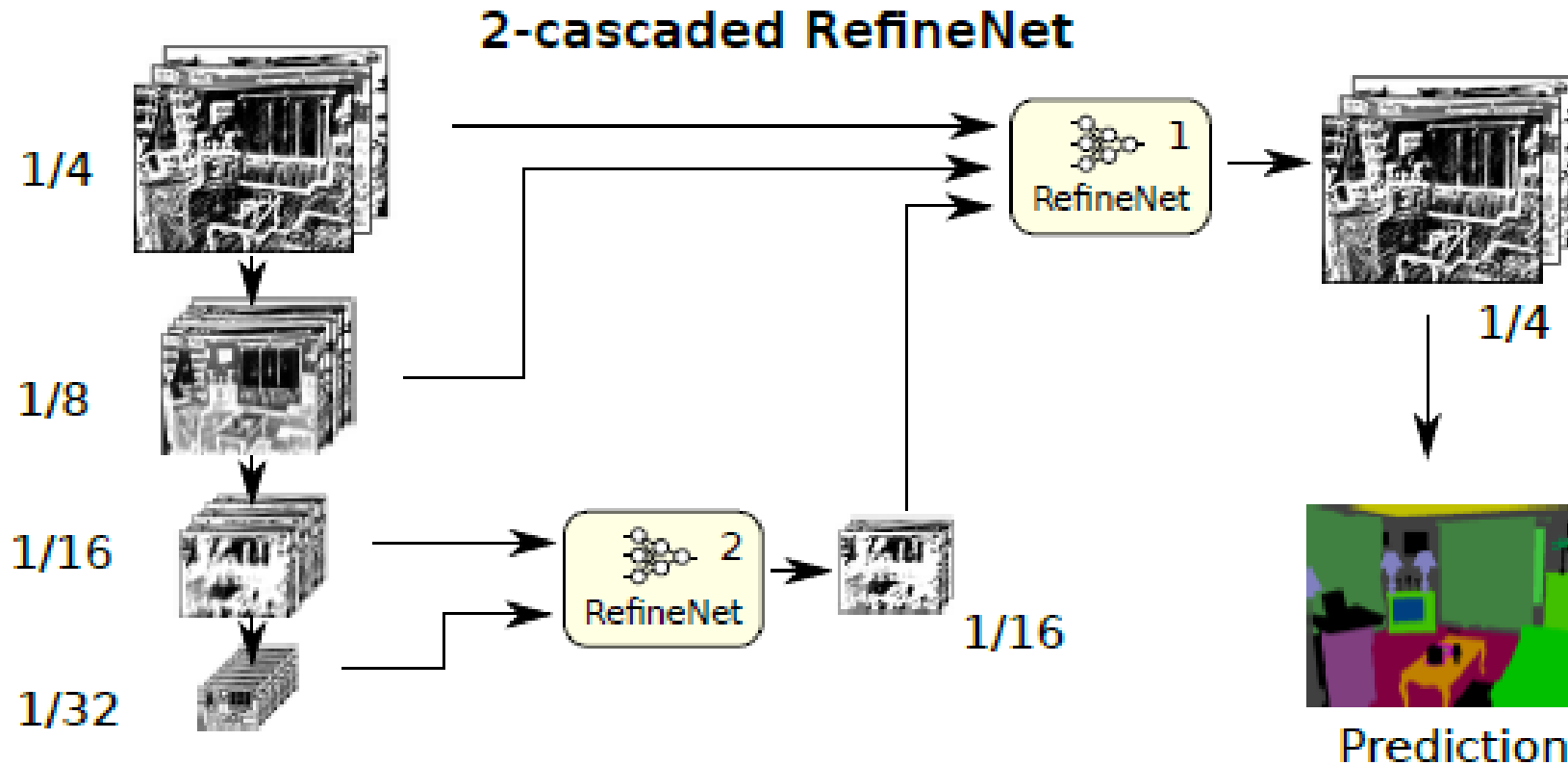
Different RefineNet Variants



(a)

Single RefineNet model: It takes all four inputs from the four blocks of [ResNet](#) and fuses all-resolution feature maps in a single process.

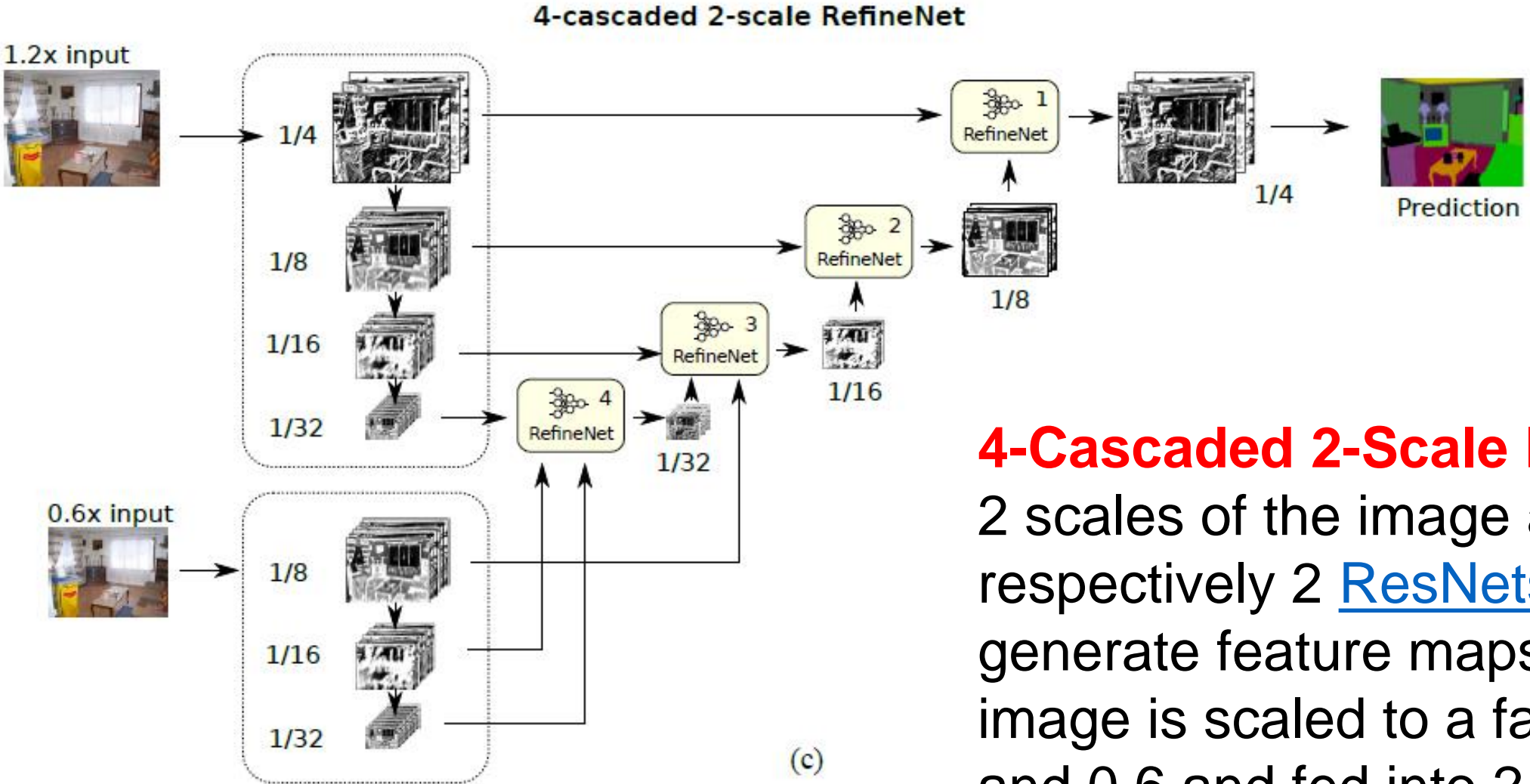
Different RefineNet Variants



(b)

2-Cascaded RefineNet: It employs only two RefineNet modules instead of four. The bottom one, RefineNet-2, has two inputs from [ResNet](#) blocks 3 and 4, and the other one has three inputs, two coming from the remaining [ResNet](#) blocks and one from RefineNet-2.

Different RefineNet Variants

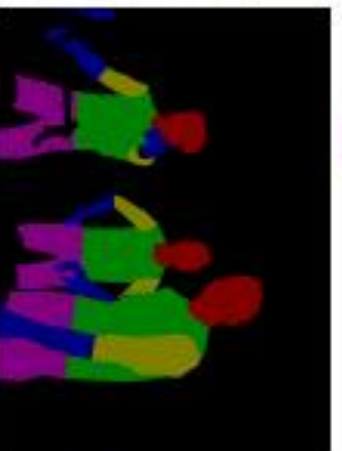
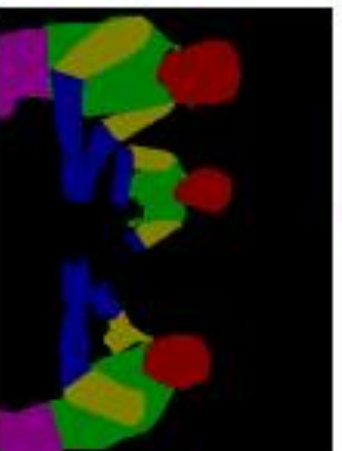
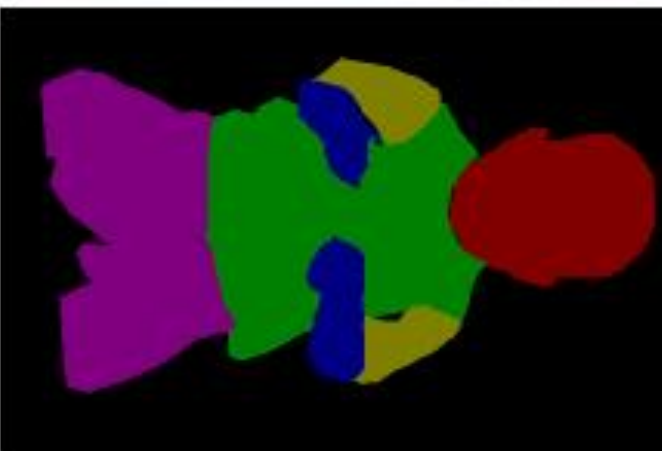


4-Cascaded 2-Scale RefineNet has the best results due to the larger capacity of the network, but it also results in longer training times.

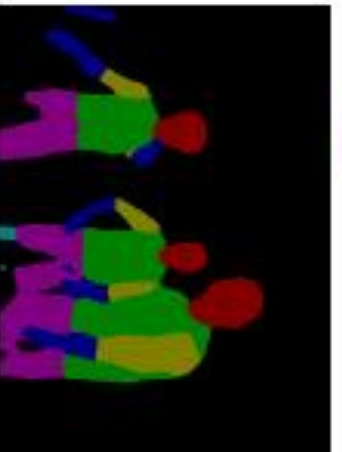
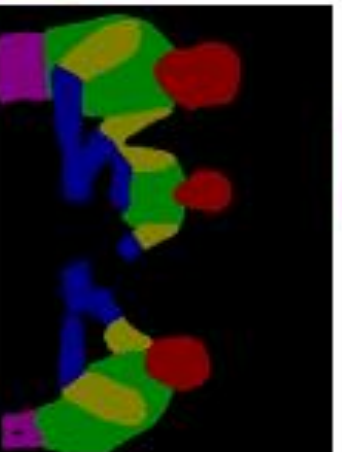
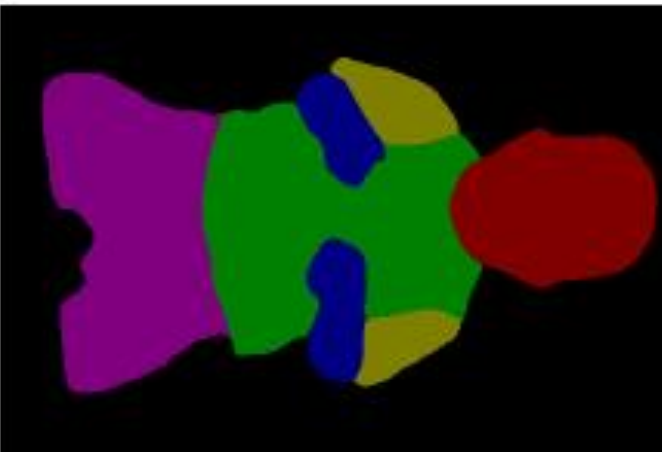
4-Cascaded 2-Scale RefineNet: 2 scales of the image as input and respectively 2 ResNets to generate feature maps. The input image is scaled to a factor of 1.2 and 0.6 and fed into 2 independent ResNets.



(a) Test Image



(b) Ground Truth



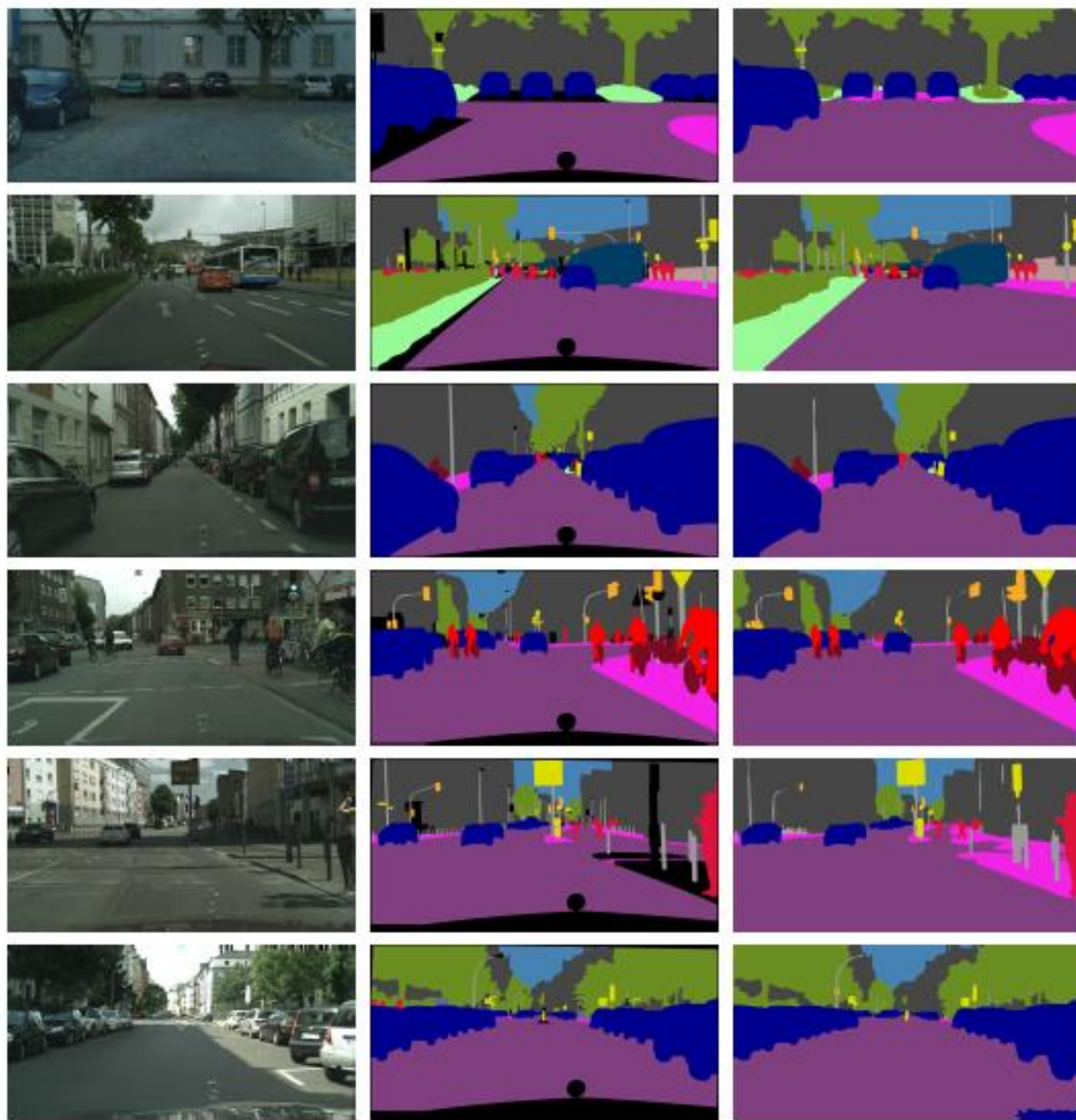
(c) Prediction



(a) Test Image

(b) Ground Truth

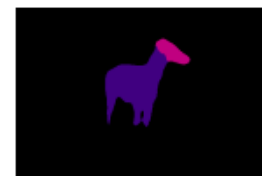
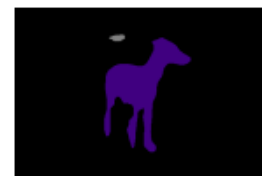
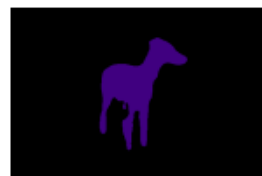
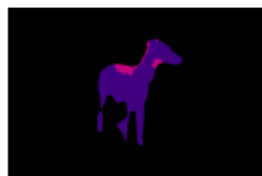
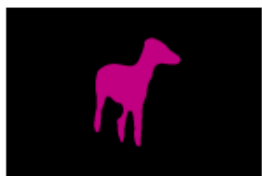
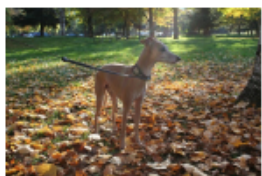
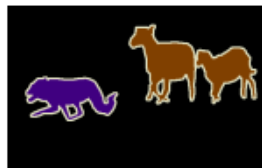
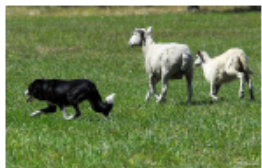
(c) Prediction



(a) Test Image

(b) Ground Truth

(c) Prediction



Image

GT

RF-101

RF-50-LW

RF-101-LW

RF-152-LW

MOB-LW

NAS-LW